



POLITECNICO
MILANO 1863

Inclusive and smart mobility

Mara Tanelli - Politecnico di Milano

mara.tanelli@polimi.it

DEWIS Symposium – Gendered and Inclusive Research and Innovation
Delft, Nov 14th 2022

My research path and main interests

Braking control...

Sergio M. Savaresi
Mara Tanelli

AIC

Advanced in
Industrial Control

Active Braking Control Systems Design for Vehicles



Vehicle control...

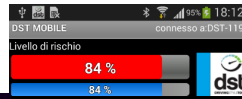
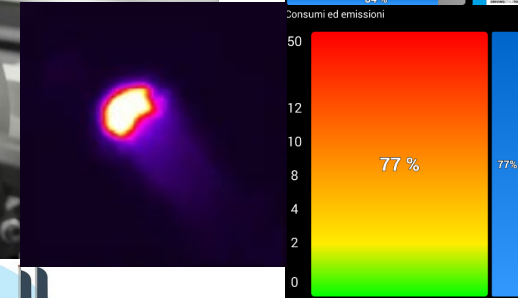
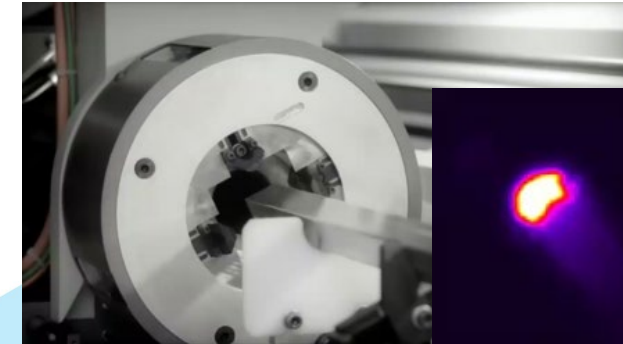
AUTOMOTIVE SERIES

MODELLING, SIMULATION AND CONTROL OF TWO-WHEELED VEHICLES

EDITORS
MARA TANELLI
MATTEO CORNO
SERGIO MATTEO SAVARESI

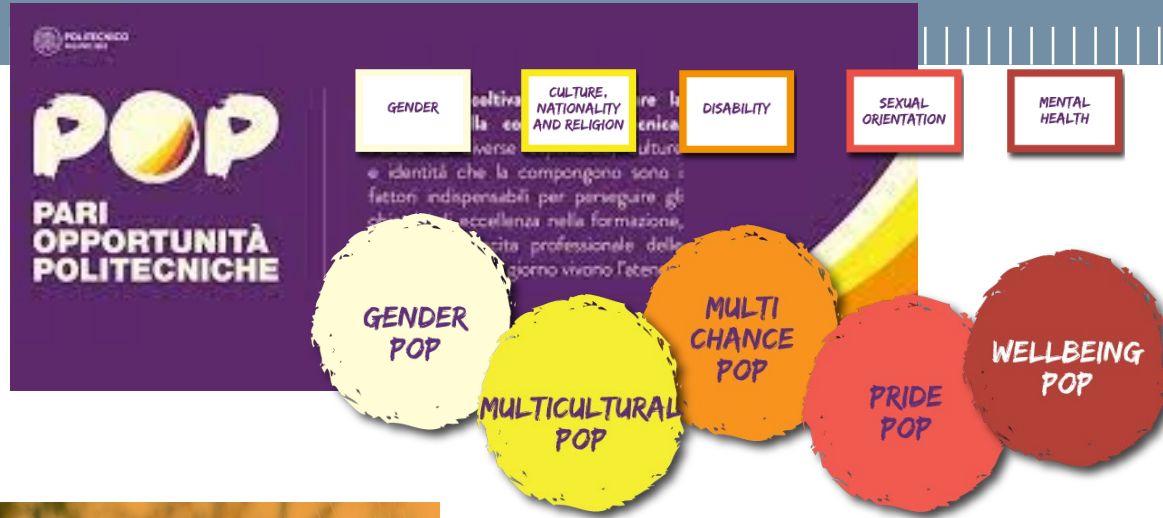


Smart Mobility and industrial analytics...



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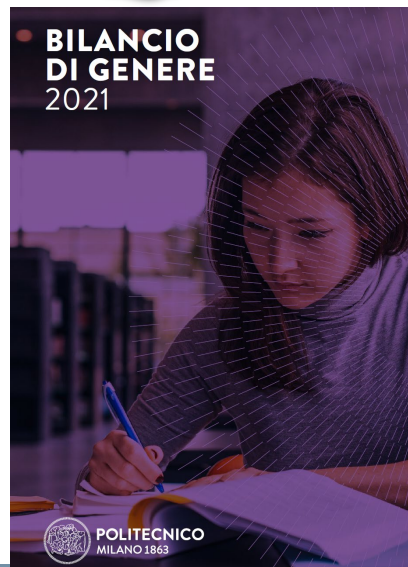
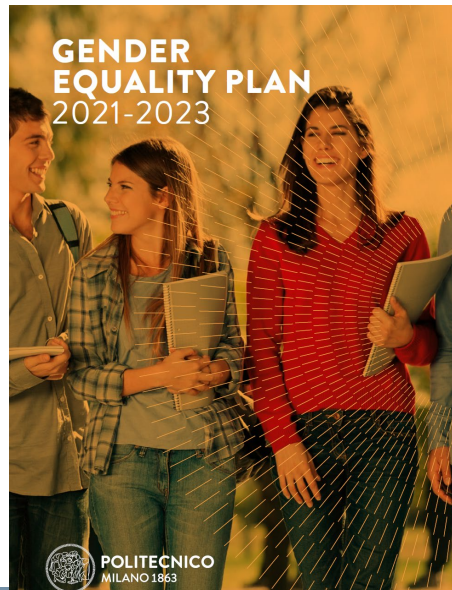
Civic engagement and institutional services



**Member of STEMI
Structure for the Ecological
Transition of Mobility and
Infrastructures @MIMS**



**Cambiamenti climatici,
infrastrutture e mobilità**



**IEEE
Control Systems
Society™**

**Chair of the Technical
Committee on
Automotive Controls**



Decarbonizzare i trasporti
Evidenze scientifiche e proposte di policy

Aprile 2022



Main focus of this talk: smart, diversity-aware and inclusive mobility... WHY?



Climate emergency
and decarbonization goals



Prominent role of **road transport** in gas emissions and energy consumption



Real changes are possible only being aware of the **human-factor centrality**

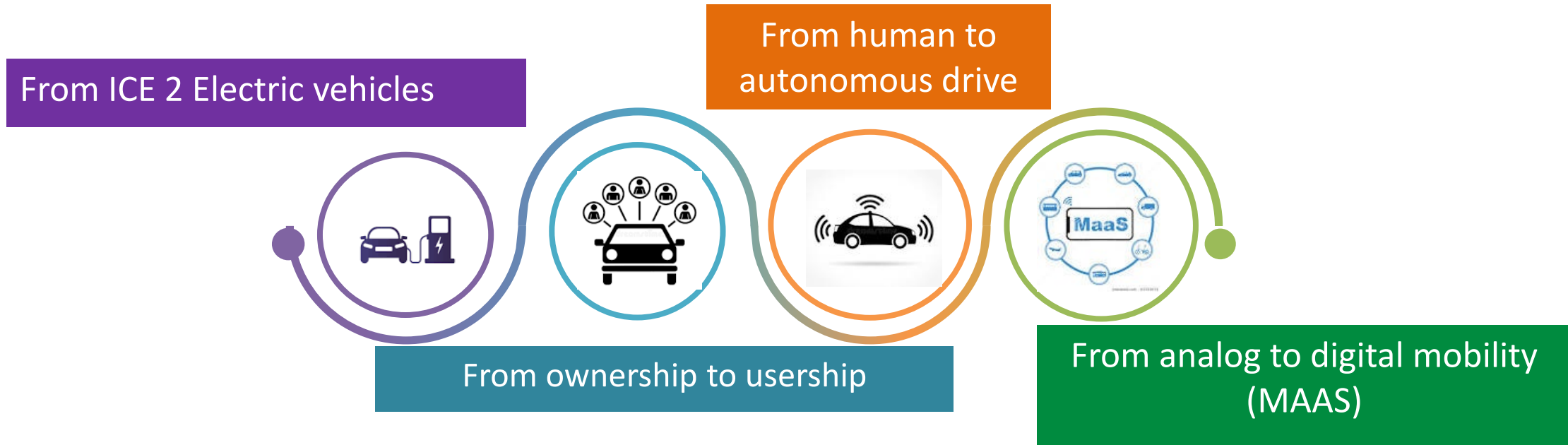


There is a strong need of sustainable and inclusive mobility solutions accounting for individual diversity, captured by socio-economic factors that go beyond mobility habits



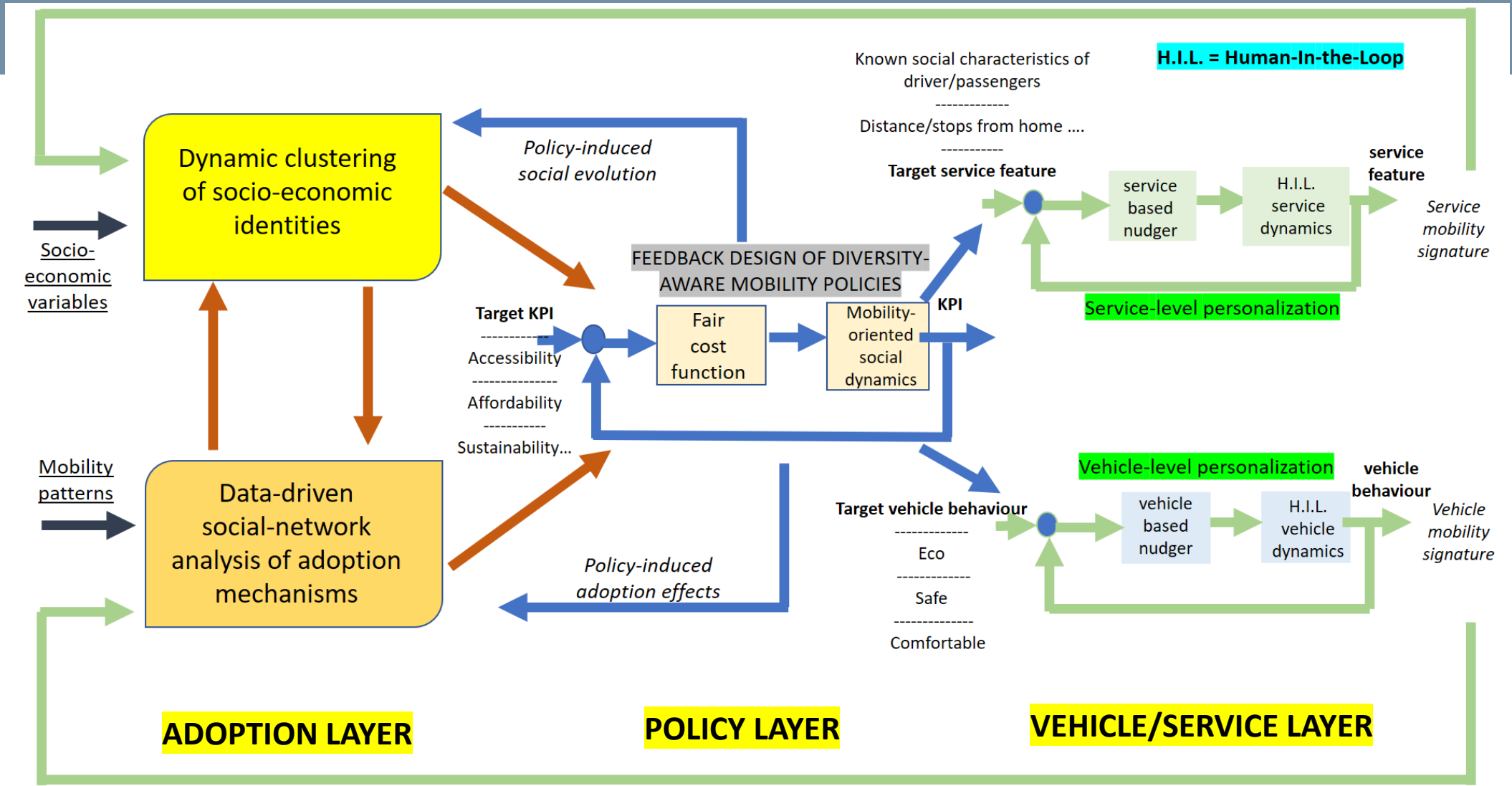
The evolution of mobility and its users: a socio-technical problem

Mobility is undergoing disruptive changes



- Key to success is **massive adoption** → **substantial individual behavioural changes**
- Technology players **cannot ignore societal challenges**: the gender gap; the digital divide; a widespread ageing; an ever-increasing multiculturalism.

How to deal with this? With a 3-layers approach





Model the attitude towards innovative mobility solutions

Adopt a **data-driven** approach to:

- ✓ Extract the **main socio-economic drivers** to the adoption of innovative mobility solutions
- ✓ Embed the selected information in **compact indicators** → **Users' mobility-DNAs**
- ✓ Enable a **realistic picture of the adoption processes**



Study the adoption dynamics through network analysis

Build **social networks** that:

- ✓ **Connect users** according to specific proximity measures
- ✓ **Model the adoption dynamics of new mobility paradigms** within a network-based evolution accounting for opinions' spread
- ✓ Give a basis model on which to test **fair policies** to support adoption

Adoption layer: example of results

The Sharing-DNA is a compact, yet comprehensive, tool **to characterize individual attitude towards shared mobility** accounting for socio-economic and behavioural factors

Available Data

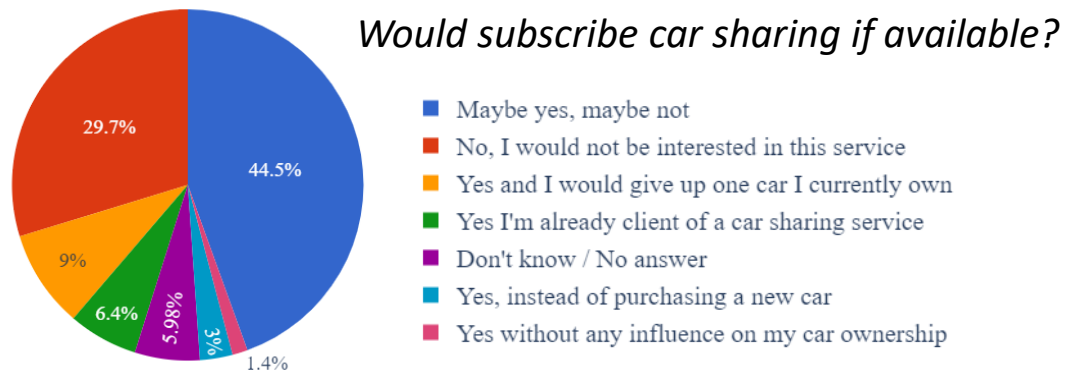
- **2014 EU survey** on mobility issues
- **39 questions** related to personal information and mobility habits



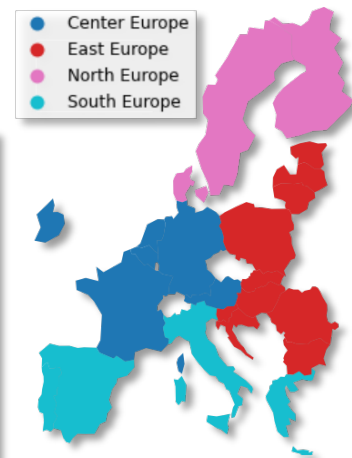
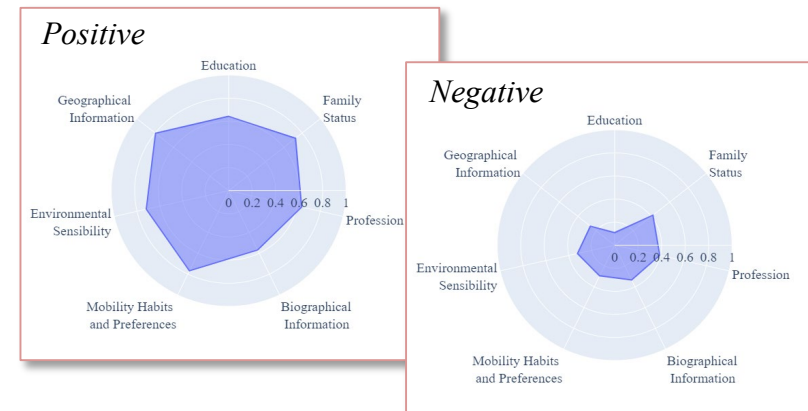
The objective

Extract primary socio-economic drivers to the adoption of sharing services

Target question



Results and applications

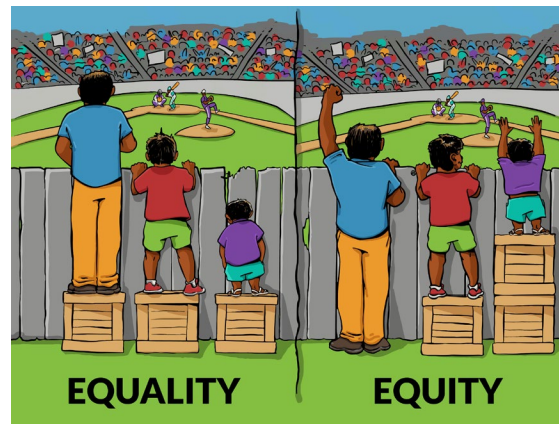


The policy layer

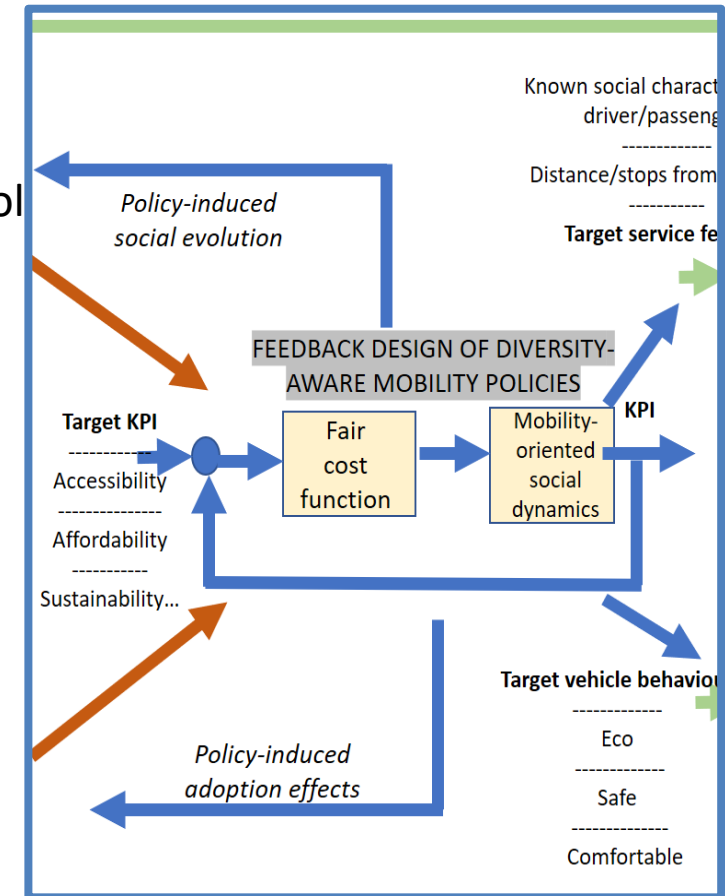
Design policies that enact social-justice principles

Enable an extended cost-benefit analysis to design policies that:

- ✓ **Foster adoption** while **accounting for individual features and diversity** in the users' pool
- ✓ Allow one to formulate policies that **quantify social justice principles and fairness attributes** in the same way we usually do for performance and budget constraints (e.g., **equality and equity**)
- ✓ **Enable closed-loop policy evaluation at design time**



Everyone benefits from the same support
Individual support induces equal access



The policy layer: example of results

The Fair-MPC is a **fair model predictive control system** and represents an innovative tool to design **dynamic fair policies** that **quantitatively** account for social justice

The **global output** defined according to the agents' dynamics described by a set of **LTI systems**

Centralized MPC

Agents' target

$$\underset{\tilde{\mathbf{u}}}{\text{minimize}} \quad J(\tilde{\mathbf{u}}, \tilde{\mathbf{y}}, \tilde{\mathbf{r}}) \quad (4a)$$

$$\text{s.t.} \quad \tilde{\mathbf{x}}_{k+1}^i = \mathbf{A}^i \tilde{\mathbf{x}}_k^i + \mathbf{B}^i \tilde{\mathbf{u}}_k^i, \quad \forall i \in \mathcal{I}^N, \forall k \in \mathcal{I}_0^L, \quad (4b)$$

$$\tilde{\mathbf{y}}_k^i = \mathbf{C}^i \tilde{\mathbf{x}}_k^i + \mathbf{D}^i \tilde{\mathbf{u}}_k^i, \quad \forall i \in \mathcal{I}^N, \forall k \in \mathcal{I}_0^L, \quad (4c)$$

$$\tilde{\mathbf{x}}_0^i = \mathbf{x}_t^i, \quad \forall i \in \mathcal{I}^N, \quad (4d)$$

$$\tilde{\mathbf{u}}_k^i \in \mathcal{U}^i, \tilde{\mathbf{y}}_k^i \in \mathcal{Y}^i, \quad \forall i \in \mathcal{I}^N, \forall k \in \mathcal{I}_0^L, \quad (4e)$$

$$\sum_{i=1}^N \|\tilde{\mathbf{u}}_k^i\|_1 \leq \bar{U}_t, \quad \forall k \in \mathcal{I}_0^L, \quad (4f)$$

Budget constraint:
agents share the same inputs to achieve their objectives

Fair objective function

$$J(\tilde{\mathbf{u}}, \tilde{\mathbf{y}}, \tilde{\mathbf{r}}) = J_p(\tilde{\mathbf{y}}, \tilde{\mathbf{r}}) + J_u(\tilde{\mathbf{u}}) + J_e(\tilde{\mathbf{y}}, \tilde{\mathbf{r}})$$

$$J_p(\tilde{\mathbf{y}}, \tilde{\mathbf{r}}) = \sum_{i=1}^N \sum_{k=0}^{L-1} \|\tilde{\mathbf{y}}_k^i - \tilde{\mathbf{r}}_k^i\|_{\mathbf{Q}^i}^2$$

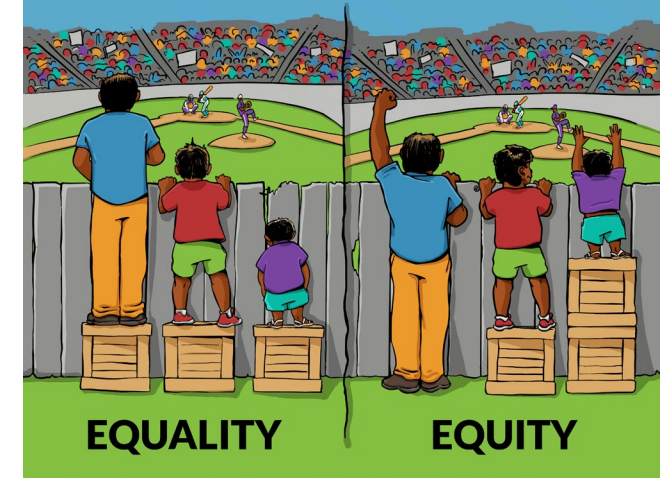
Individual Performance

$$J_u(\tilde{\mathbf{u}}) = \sum_{i=1}^N \sum_{k=0}^{L-1} \rho^i \left(\|\tilde{\mathbf{u}}_k^i\|_1 - \frac{\bar{U}_t}{N} \right)^2$$

Equality

$$J_e(\tilde{\mathbf{y}}, \tilde{\mathbf{r}}) = \sum_{i=1}^N \sum_{k=0}^{L-1} \left\| \tilde{\mathbf{e}}_k^i - \frac{1}{N} \sum_{j=1}^N \tilde{\mathbf{e}}_k^j \right\|_{\mathbf{P}^i}^2$$

Equity



Under Submission at the IEEE Transactions on Automatic Control

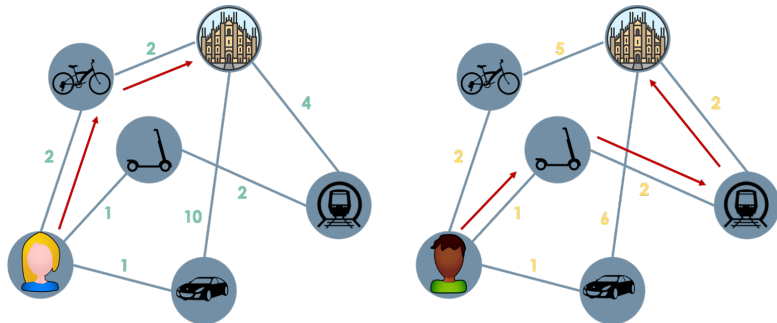
The vehicle/service layer



From models to concrete services and vehicles settings

Learn from **users' experience** to define **personalized solutions** ensuring

- ✓ **accessibility and usability** of the services
- ✓ actual **effectiveness of the designed policies** in fostering the adoption mechanisms



The final objective

Personalize the final services and vehicles that enact the mobility solutions by making them “move” towards the individual (unique) user and *viceversa*, leveraging behavioural economy (e.g., nudging) and control/decision theory:

- ✓ To **support mobility stakeholders**
- ✓ To offer each user **concrete and diversity-aware mobility solutions**
- ✓ To **realize nudging via advanced Human-Machine Interfaces** (HMIs), allowing **ADAS and autonomy adaptation**, within a diversity-aware framework

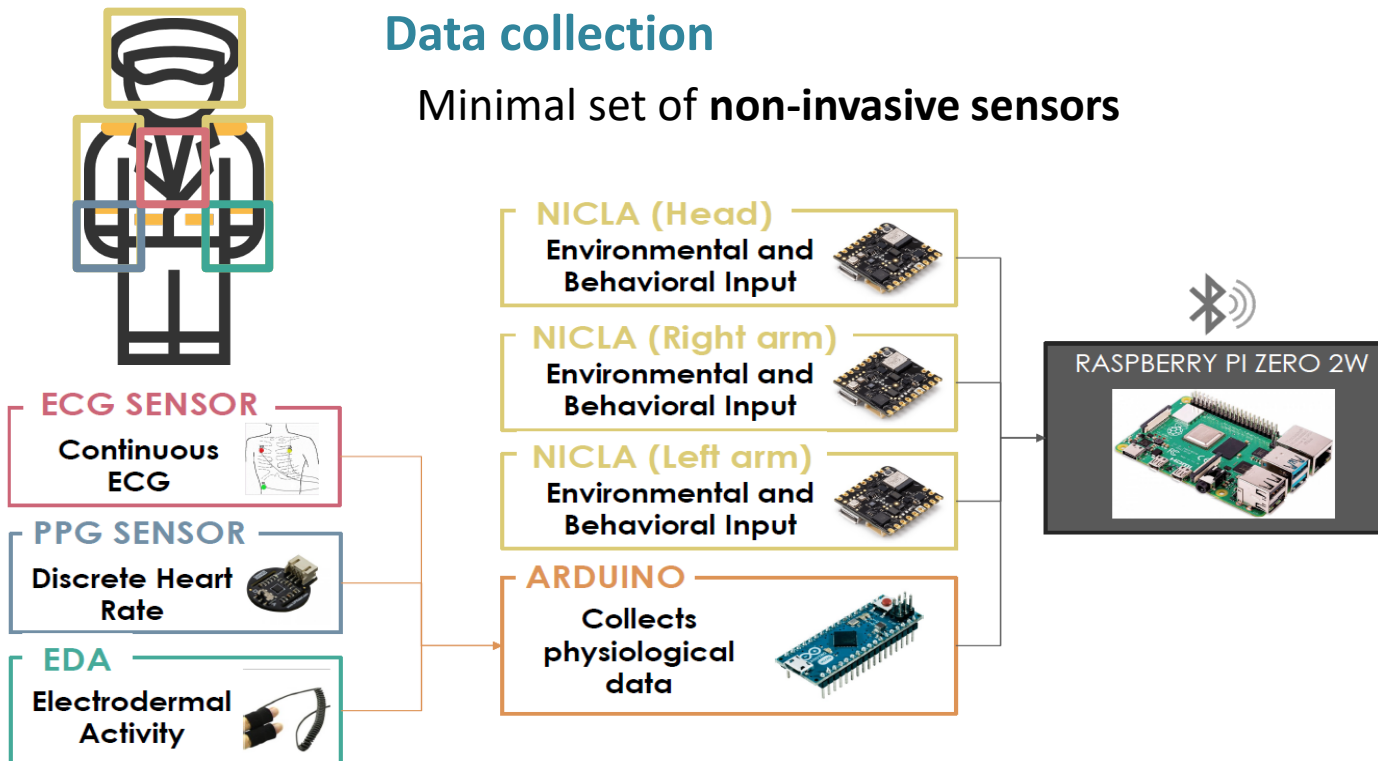


The vehicle/service level: example of results

Track a **pilot/driver psycho-physical status** in real-time through a machine learning based analysis of **environmental, behavioural and physiological data**

Data collection

Minimal set of **non-invasive sensors**



Preliminary results

Differences in normal and stressful driving conditions are especially visible in non-expert drivers. We will investigate how results change w.r.t. diversity dimensions (towards diversity-aware ADAS)

Smart and inclusive mobility: the impact

- This approach can initiate a new scientific reasoning in *mobility and beyond*, which can be applied to all contexts in which **technological variables** highly interplay with **human behaviours**.
- This new conception will open the way to **diversity-aware and socially-disaggregated data-gathering, design and interpretation processes** → great impact on public policies and product/service development, where **economically/environmentally convenient and socially just decisions** must be taken.





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mara.tanelli@polimi.it