

Non-ideal gas effects on supersonic-nozzle transfer functions

NICFD2020 - TU Delft

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29th October 2020



Outline

1 Linearised quasi-one dimensional nozzle flow

- 2 Non-ideal gas modelling
- 3 Isentropic expansion transfer function
- 4 Shocked-flow transfer function
- **5** DNS comparison





Motivation

- Few real flows are uniform
- Understand frequency response of non-ideal, non-uniform subsonic and supersonic flow
- Useful for many physical applications e.g. expansion between turbine blades jet engines regions of flow that can be modelled as such
- Quasi-1D offers 'simple' framework



Linearised quasi-one dimensional nozzle flow

Governing equations for inviscid, quasi-one dimensional flow:

$$\frac{\partial}{\partial t} \begin{bmatrix} \rho \\ \rho u \\ \rho e_t \end{bmatrix} + \frac{\partial}{\partial x} \begin{bmatrix} \rho u \\ \rho u^2 + \rho \\ u(\rho e_t + \rho) \end{bmatrix} + \frac{1}{A} \frac{\mathrm{d}A}{\mathrm{d}x} \begin{bmatrix} \rho u \\ \rho u^2 \\ u(\rho e_t + \rho) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

with the arbitrary gas equation of state (EoS):

$$p = p(\rho, e)$$
 where $e = e_t - \frac{u^2}{2}$



Linearised form obtained by assuming a harmonic perturbation:

$$q(x,t) = \underbrace{\bar{q}(x)}_{baseflow} + \underbrace{\epsilon \, \underline{q}(x)'}_{perturbation} e^{-i\omega t} \quad ext{with} \quad \epsilon \ll 1, \quad \omega \in \mathbb{R}_{>0}$$

which yields:

$$\mathbf{C}\frac{\mathrm{d}}{\mathrm{d}x}\begin{bmatrix}\rho'\\u'\\p'\end{bmatrix} = \left(\mathbf{B} + \mathrm{i}\frac{L}{\lambda}\mathbf{I}\right)\begin{bmatrix}\rho'\\u'\\p'\end{bmatrix}$$
(1)

No assumption made on reduced wavelength (λ/L) i.e. transfer function (TF) dependent on frequency.



Boundary conditions: strictly supersonic inlet with entropy perturbation.



Shocked case: Linearised Rankine-Hugoniot conditions used.



Non-ideal gas modelling

In the paper:

- ideal gas law used as reference
- non-ideal effects illustrated with van der Waals gas law operating close to the critical point

Preliminary results:

• CoolProp: Span-Wagner multi-parameter EoS for D6



Non-ideal gas modelling

 $({\it p}{\rm -}\vartheta)$ space of interest for van der Waals with $\gamma=1.013$ representative of PP10





Isentropic expansion transfer function

For fixed geometry and operating range, the TF is dependant on 2 parameters:

- mass flow \dot{m}
- reduced perturbation wavelength λ/L

Scan reduced frequency space and plot transfer function over the chosen λ/L range



Isentropic expansion transfer function





Isentropic expansion transfer function





Isentropic expansion transfer function





Shocked-flow transfer function

Adding a shock requires specifying two additional conditions:

- outlet thermodynamic condition for the base-flow
- outlet perturbation condition

We choose:

- Shock placed at $\bar{x}_s/L = 2/3 \rightarrow$ determines outlet conditions
- Non-reflecting outlet and no forcing



Shocked-flow transfer function



Along isentrope defined by the point $(p, T) = (0.13p_c, T_c)$.



DNS comparison

Comparison to time integration of full non-linear equations with linear domain perturbation ($\epsilon \sim 10^{-3}$). Numerics:

- fully explicit (time \rightarrow RK3, space \rightarrow 4th order centred FD)
- arbitrary gas characteristic boundary conditions
- artificial bulk viscosity to capture shock

With sufficient resolution to resolve the shock displacement in the linear regime.



DNS comparison

Results for $\lambda/L=$ 1, $\epsilon=$ 4 imes 10⁻³ after 10 periods





DNS comparison

Results for $\lambda/L=$ 1, $\epsilon=4\times10^{-3}$ after 10 periods





Summary: isentropic expansion



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Summary: shocked flow





Conclusion

- highlighted non-ideal impact transfer function ('filter behaviour')
- shock properties can be exploited (e.g. maximise/minimise a certain fluctuation)
- linear analysis can complement steady-state analysis



Thank you for your attention! Q&A



Realistic equation of state

EoS call replaced with CoolProp call to properties of Siloxane D6



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Realistic equation of state

Results for siloxane D6:





Matrix coefficients for LEE

$$\begin{bmatrix} \bar{u} & \bar{\rho} & 0\\ 0 & \bar{u} & \frac{1}{\bar{\rho}}\\ 0 & \bar{\rho}c^2 & \bar{u} \end{bmatrix} \frac{\mathrm{d}\mathbf{q}'}{\mathrm{d}x} = \\ \begin{pmatrix} \frac{1}{(\bar{M}^2 - 1)A} \frac{\mathrm{d}A}{\mathrm{d}x} \begin{bmatrix} -\tilde{c}\bar{M}^3 & \bar{\rho} & 0\\ \frac{\bar{M}^2\tilde{c}^2}{\bar{\rho}} & -\bar{M}\tilde{c} & 0\\ -\bar{M}^3\tilde{c}^2(\tilde{c} + 2\bar{\rho}\tilde{c}_{\rho}) & \bar{\rho}\tilde{c}^2 & -2\bar{M}^3\tilde{c}^2\tilde{c}_{p}\bar{\rho} \end{bmatrix} - i\omega \mathbf{I} \end{pmatrix} \mathbf{q}' \\ \text{where } \tilde{c} = c(\bar{\rho},\bar{p}), \ \tilde{c}_{\rho} = (\partial c/\partial \rho)_{p}(\bar{\rho},\bar{p}), \ \tilde{c}_{p} = (\partial c/\partial p)_{\rho}(\bar{\rho},\bar{p})$$



Linearised Rankine-Hugoniot equations

$$\begin{bmatrix} \bar{u}_{b} & \bar{\rho}_{b} & 0\\ \bar{u}_{b}^{2} & 2\bar{\rho}_{b}\bar{u}_{b} & 1\\ -\frac{\partial\varphi}{\partial\rho}\Big|_{b} & 0 & 1 \end{bmatrix} \begin{bmatrix} \rho_{b}'\\ u_{b}'\\ \rho_{b}' \end{bmatrix} + \begin{bmatrix} -i\omega[\bar{\rho}]]\\ \frac{\bar{\rho}_{a}^{2}\bar{u}_{a}^{2}}{A}\frac{dA}{dx}[\bar{1}\bar{\rho}]]\\ \left(\frac{\partial\varphi}{\partial\rho}\frac{d\bar{p}}{dx} + \frac{\partial\varphi}{\partial\rho}\frac{d\bar{\rho}}{dx}\right)\Big|_{a} + \left(\frac{\partial\varphi}{\partial\rho}\frac{d\bar{\rho}}{dx} - \frac{d\bar{p}}{dx}\right)\Big|_{b} \end{bmatrix} x_{s}' = \begin{bmatrix} \bar{u}_{a} & \bar{\rho}_{a} & 0\\ \bar{u}_{a}^{2} & 2\bar{\rho}_{a}\bar{u}_{a} & 1\\ \frac{\partial\varphi}{\partial\rho}\Big|_{a} & 0 & \frac{\partial\varphi}{\partial\rho}\Big|_{a} \end{bmatrix} \begin{bmatrix} \rho_{a}'\\ u_{a}'\\ \rho_{a}'\end{bmatrix}$$