

Airborne Wind Energy

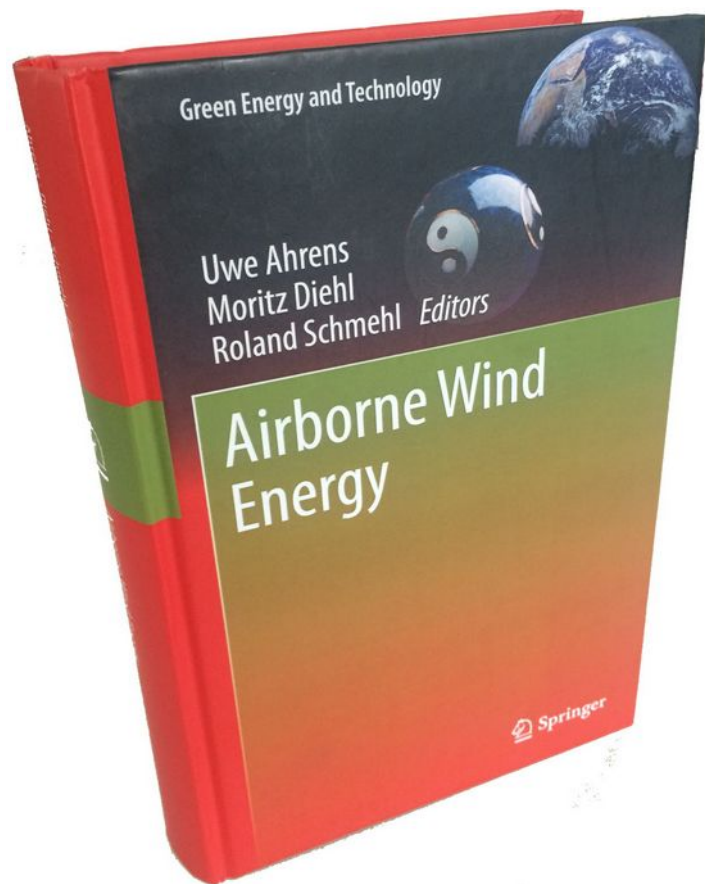
PowerWeb webinar lecture

Roland Schmehl

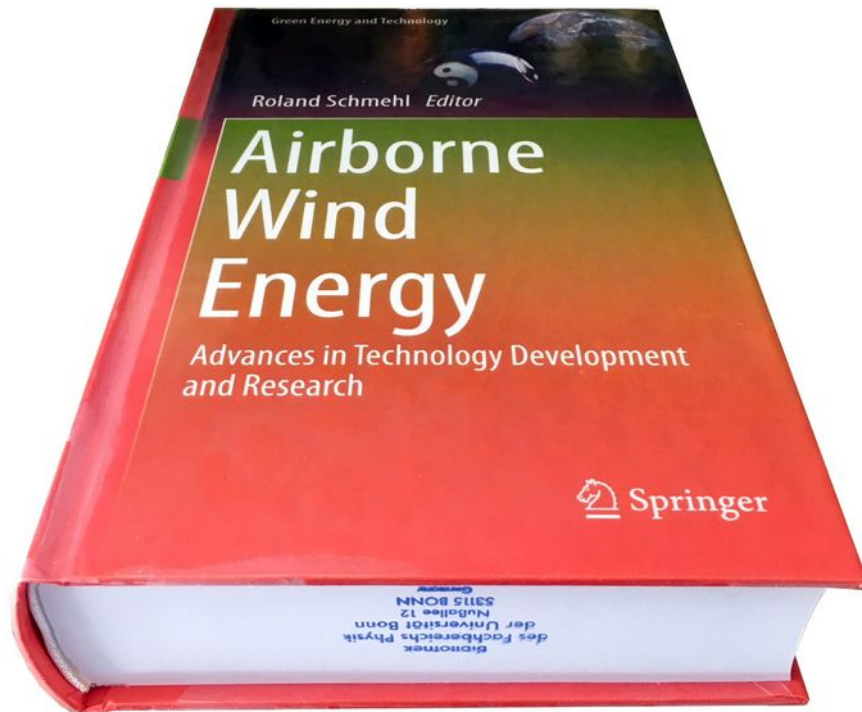


Presenter

- Associate Professor at Delft University of Technology
- Co-founder of Kitepower BV
- Coordinator of 2 H2020 projects (AWESCO & REACH)
- AWE-responsible PI in Dutch NWO project NEON
- Co-organizer of AWEC 2015, 2017 and 2019
- Co-editor and editor of 2 Springer textbooks on AWE



2013



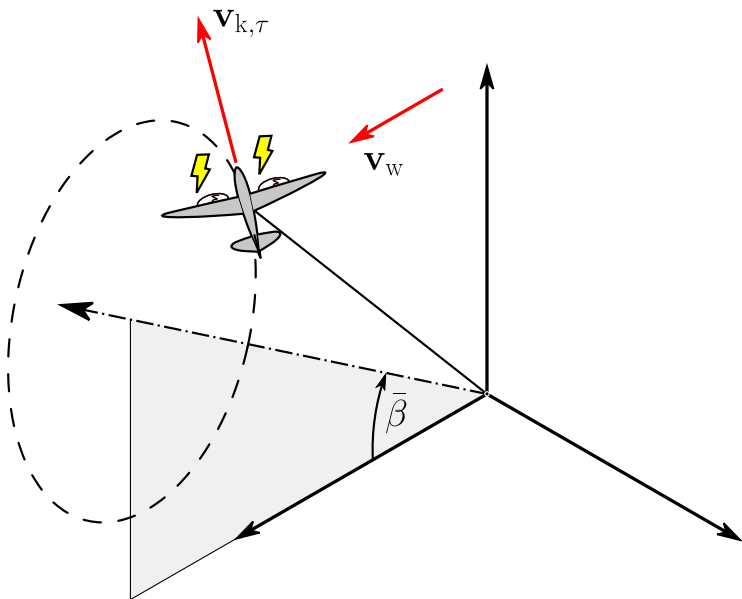
2018

Outline

- Fundamental working principles
- Classification of concepts
- Implemented technology demonstrators
- Development challenges
- Research challenges
- Development of the sector

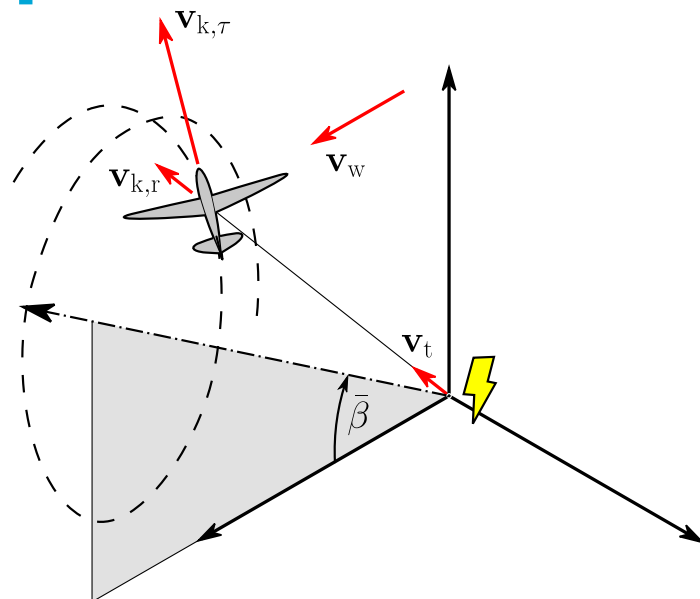
Fundamental concepts

Miles L. Loyd (1980)



Drag power:

- Flying wing \rightsquigarrow shaft power
- Shaft power \rightsquigarrow electricity ($\omega \uparrow$)
- Electricity \rightsquigarrow conductive tether



Lift power:

- Flying wing \rightsquigarrow traction force
- Traction force \rightsquigarrow shaft power ($\omega \downarrow$)
- Shaft power \rightsquigarrow electricity

Key aspects



- Consumes significantly less material
- Highly adjustable to wind resource
- Access to high altitude wind
- Increased mobility

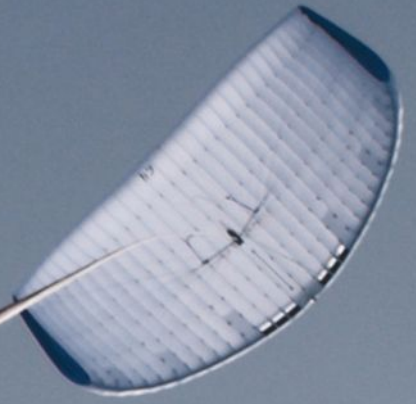
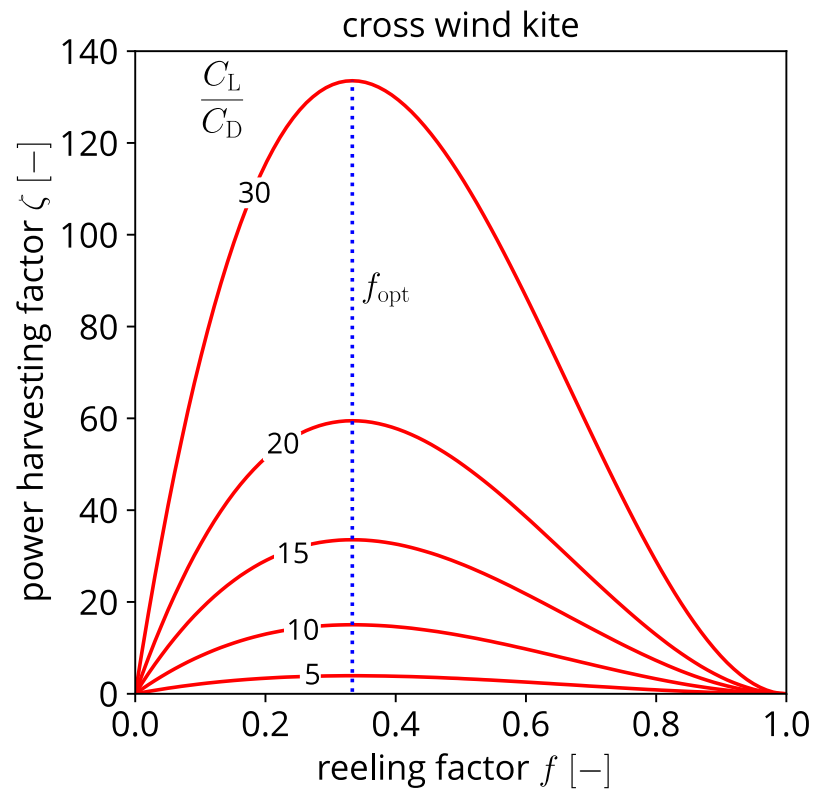
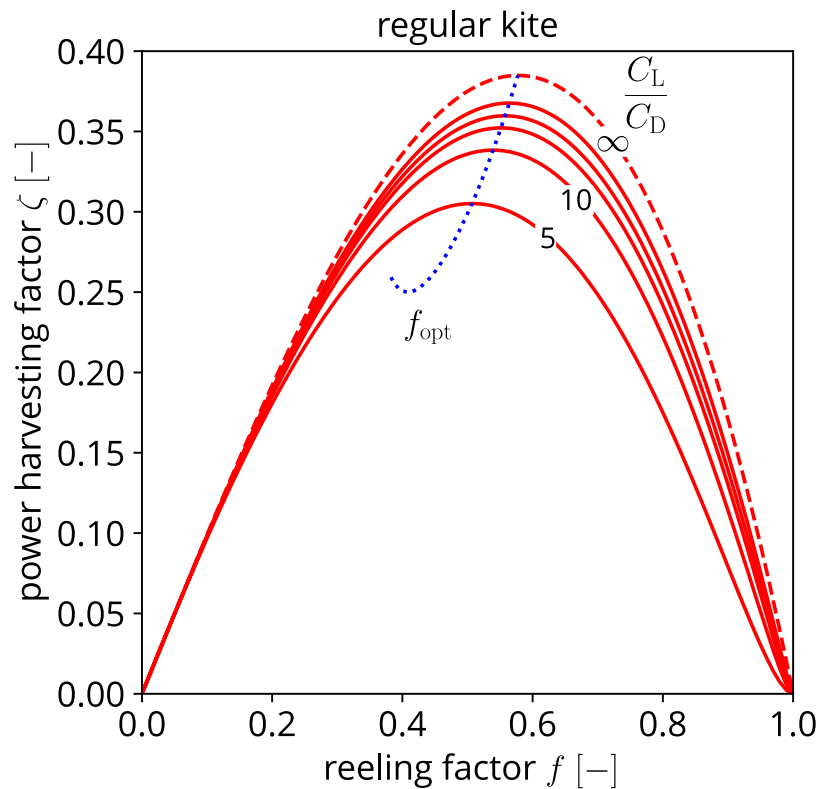


Image source: Skysails

- More complex than turbines
- Requires reliable & robust control
- Depends on high-performance materials
- Need to revise current regulatory framework



power harvesting factor $\zeta = \frac{P}{P_w S}$, wind power density $P_w = \frac{1}{2} \rho v_w^2$, reeling factor $f = \frac{v_t}{v_w}$,
 mechanical power P , wing surface area S

Technology demonstrators

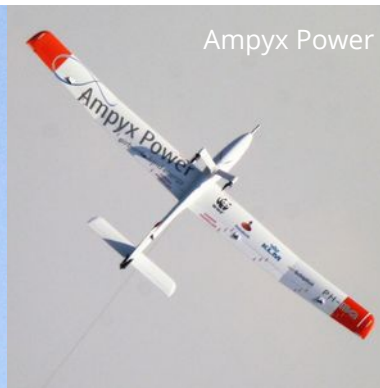
Kitepower



Enerkite



Ampyx Power



Kitemill



Twingtec



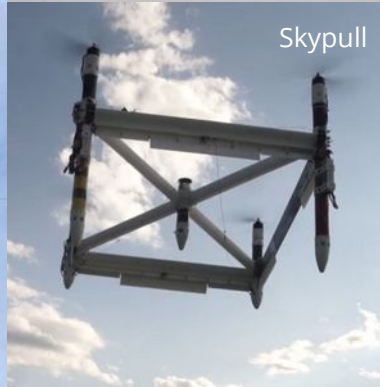
Skysails



KPS



Skypull



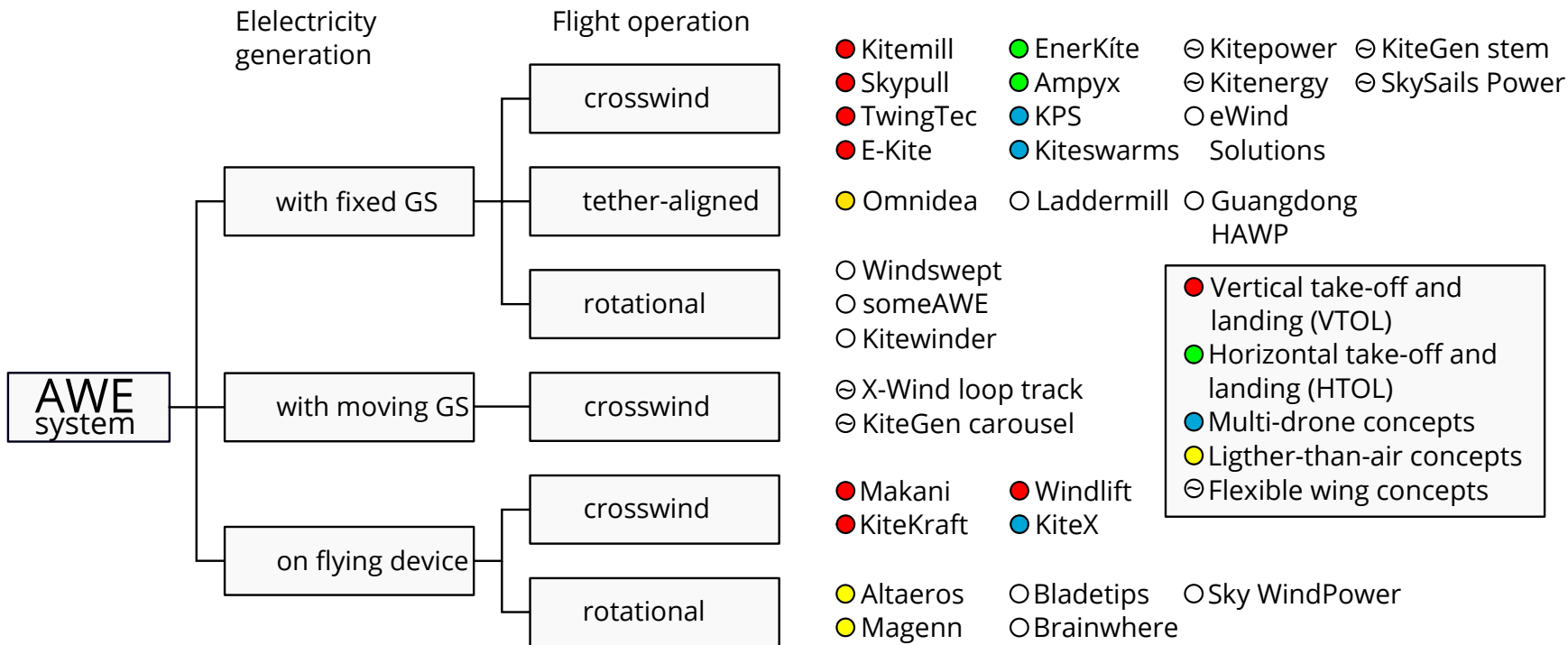
Windswept



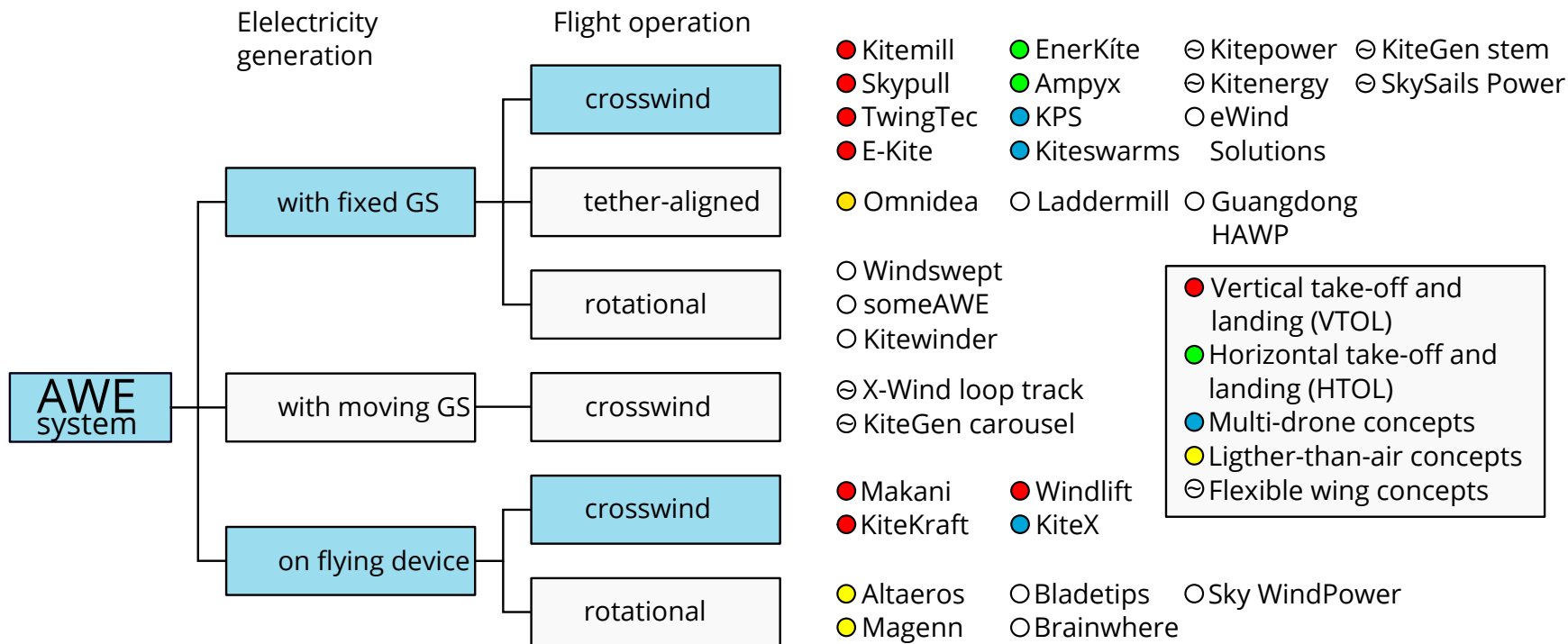
eWindSolutions



AWES classification



AWES classification



Further reading: awesco.eu/awe-explained

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Airborne Wind Energy

An introduction to an emerging technology.

Roland Schmehl

20 Jun 2019



Airborne wind energy (AWE) is the conversion of wind energy into electricity using tethered flying devices. Some concepts combine onboard wind turbines with a conducting tether, while others convert the pulling power of the flying devices on the ground. Replacing the tower of conventional wind turbines by a lightweight tether substantially reduces the material consumption and allows for continuous adjustment of the harvesting altitude to the available wind resource. The decrease in installation cost and increase in capacity factor can potentially lead to a substantial reduction of the cost of wind energy. Wind at higher altitudes is also considered to be an energy resource that has not been exploited so far.

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[Historical perspective](#)[Development as an industry](#)[Presently pursued concepts](#)[Conclusions](#)

Technology demonstrators

- Makani
- Ampyx
- Twingtec
- Kitepower

Wing7 (30 kW)



M600 (600 kW)





AP-2 (50 kW)



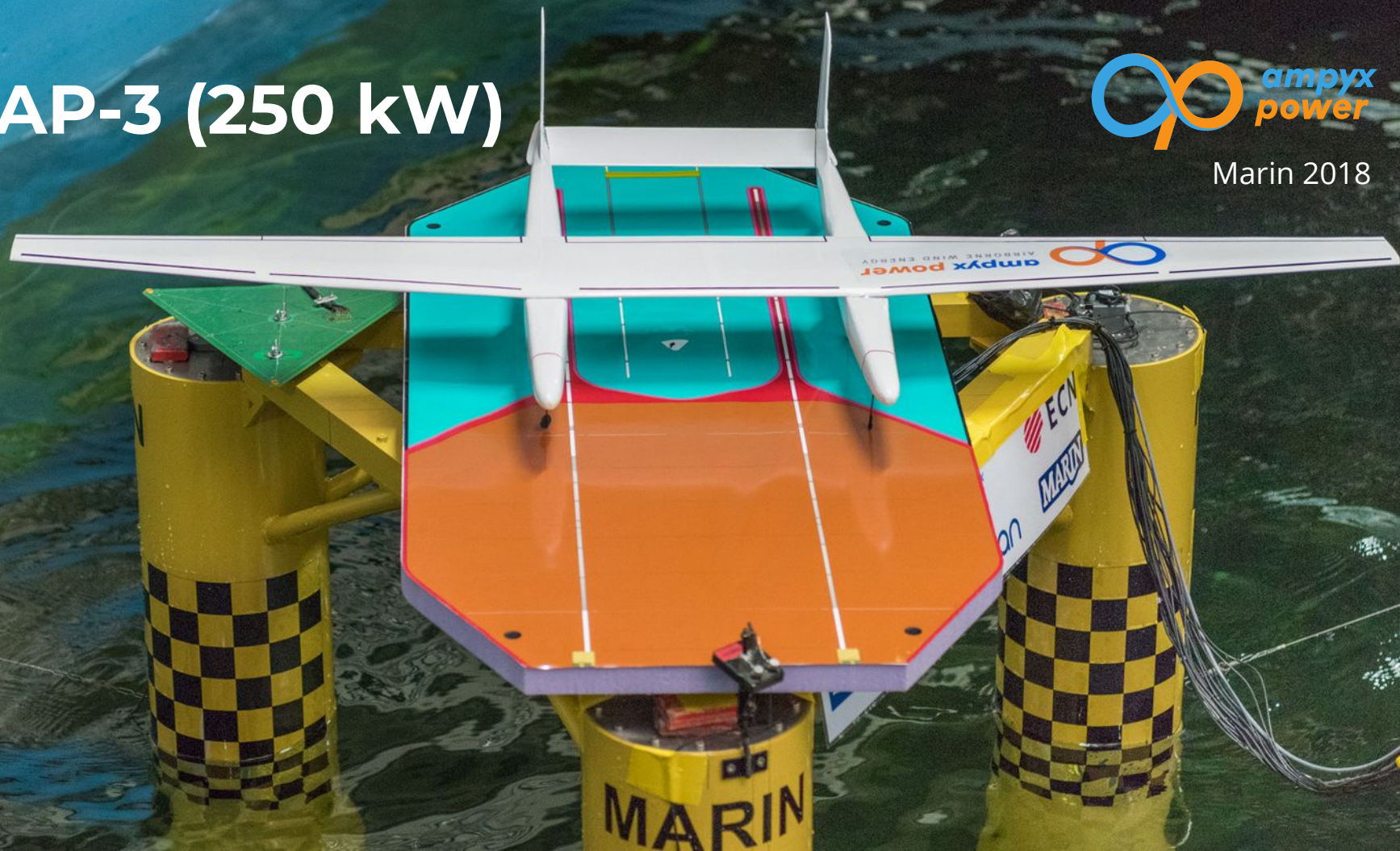
Noordoostpolder 2013



AP-3 (250 kW)

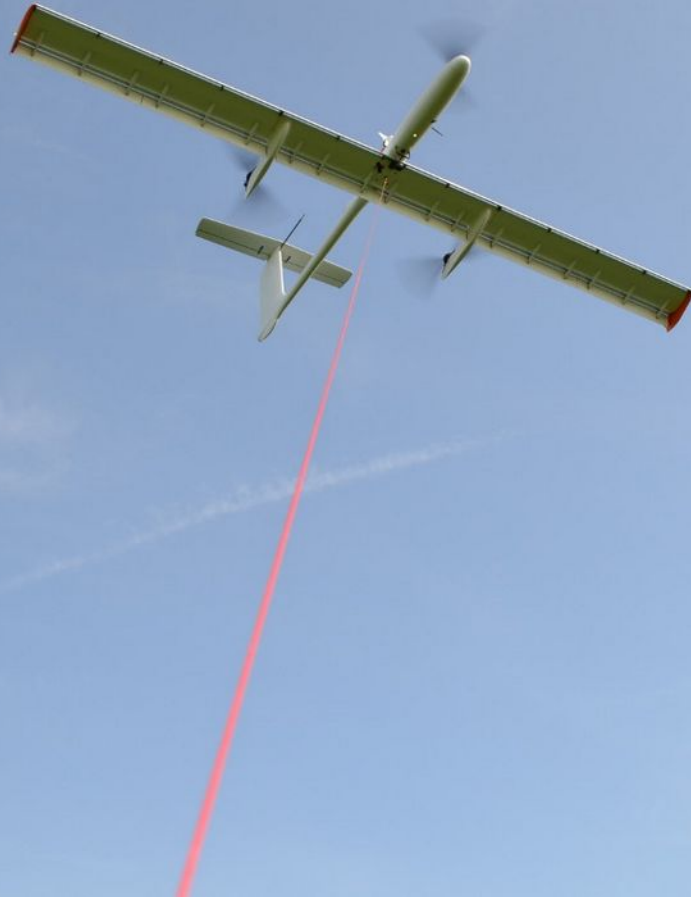


Marin 2018











TwingTec pilot next to turbine with same power

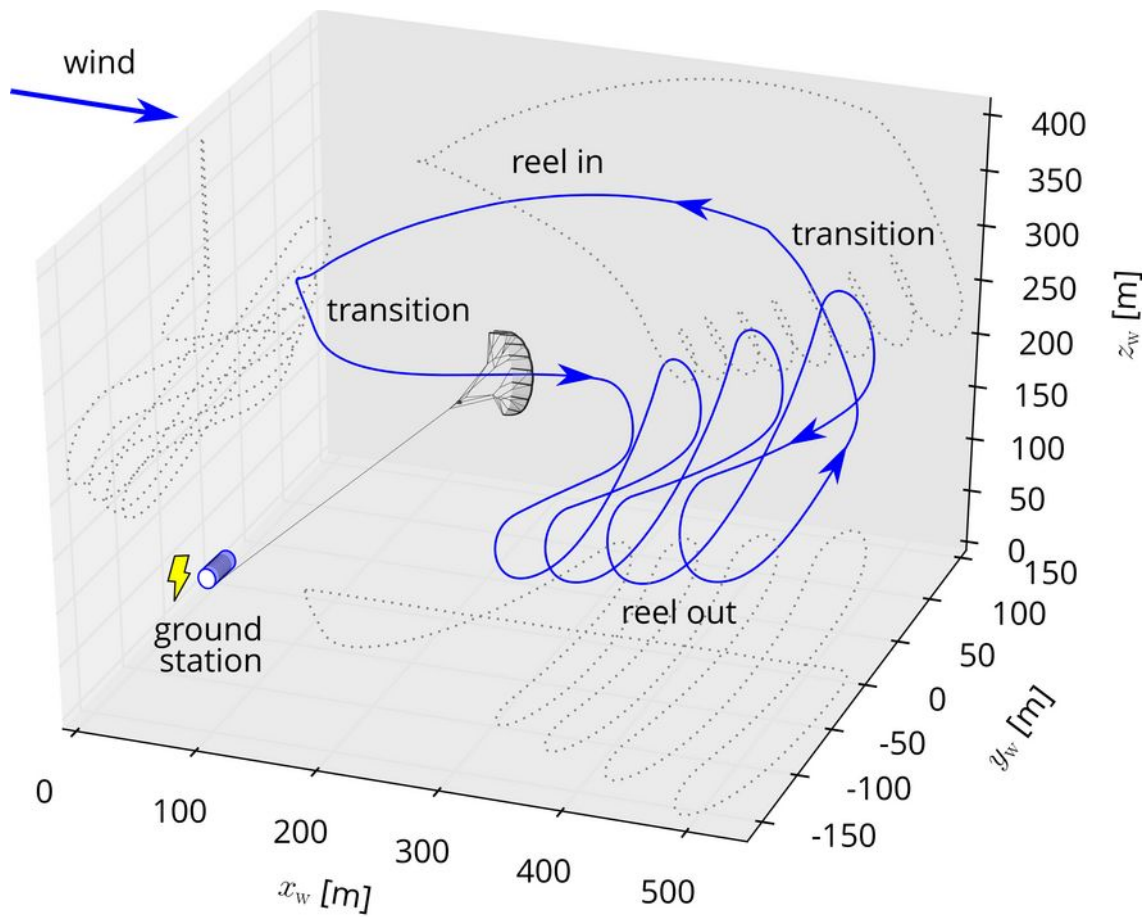


25 kW kite power system

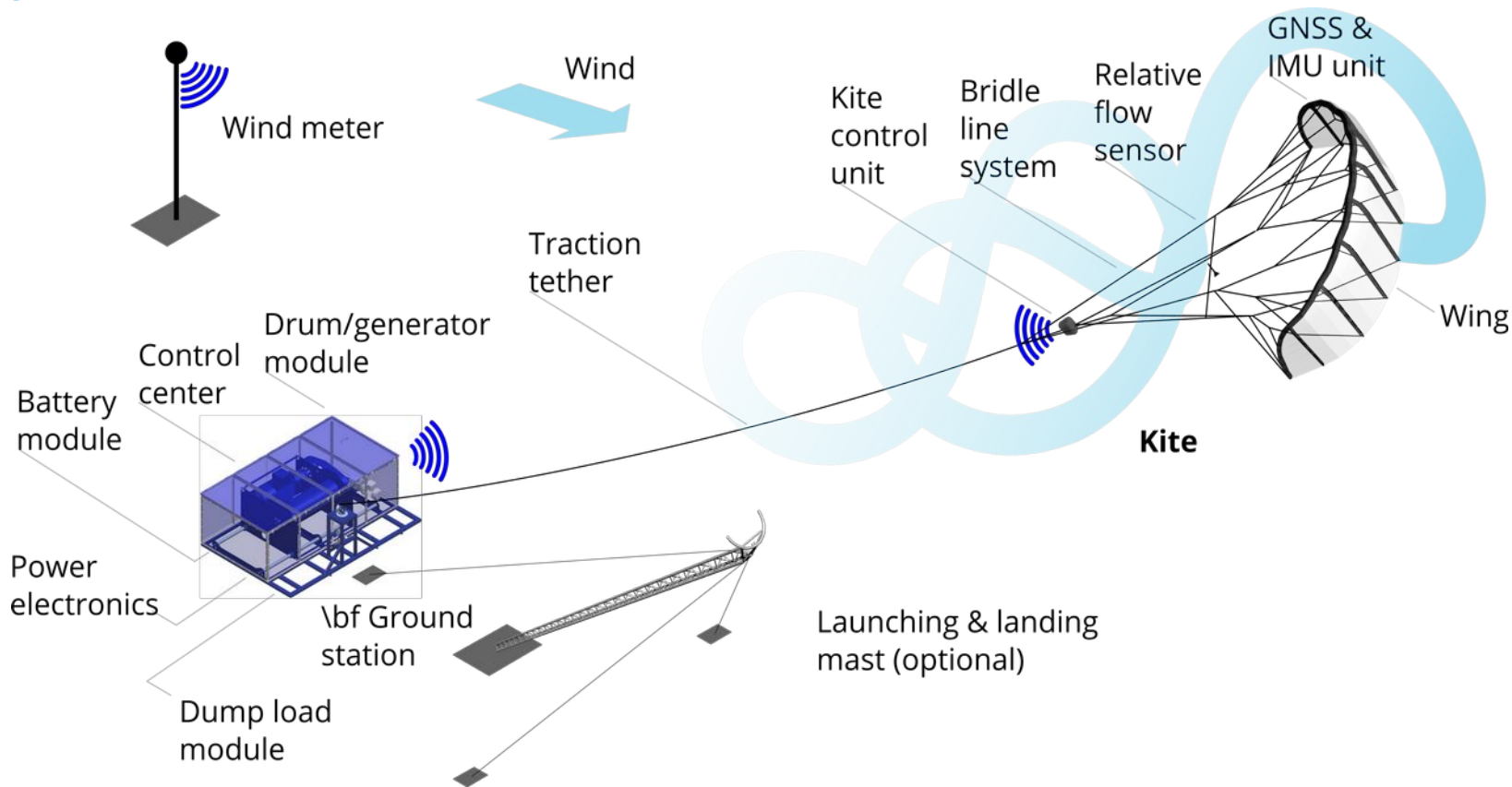
 **TU Delft**

2012

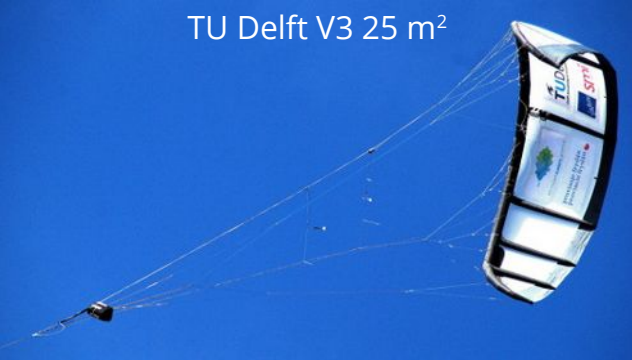




System components



TU Delft V3 25 m²



Genetrix Hydra 14 m²

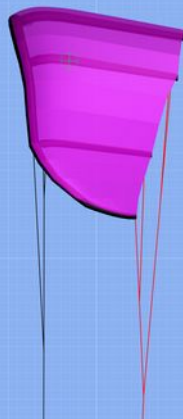


TU Delft V3 25 m²

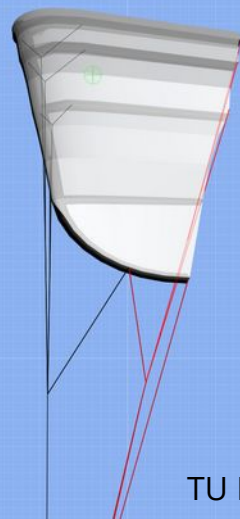




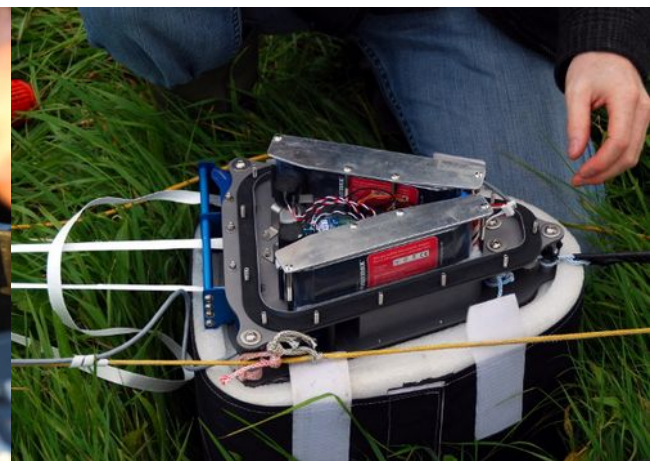
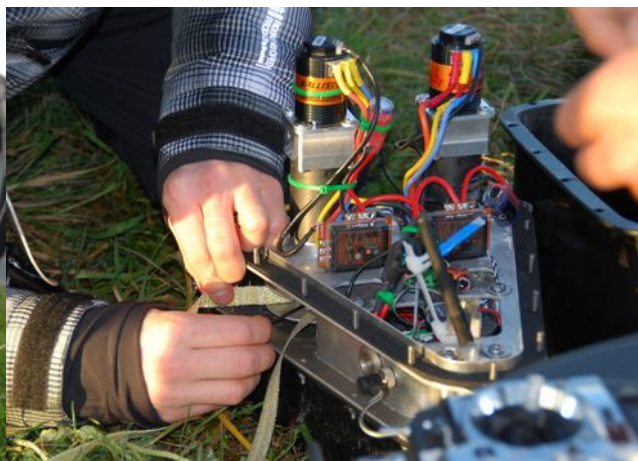
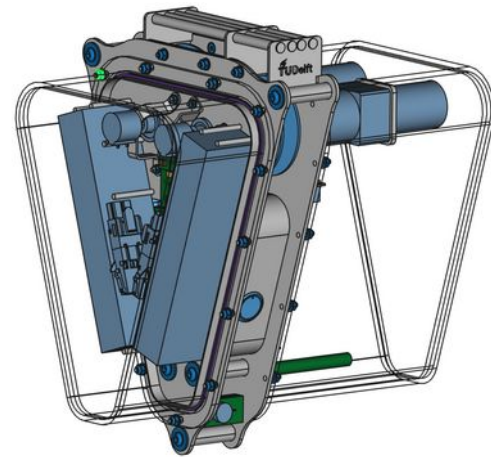
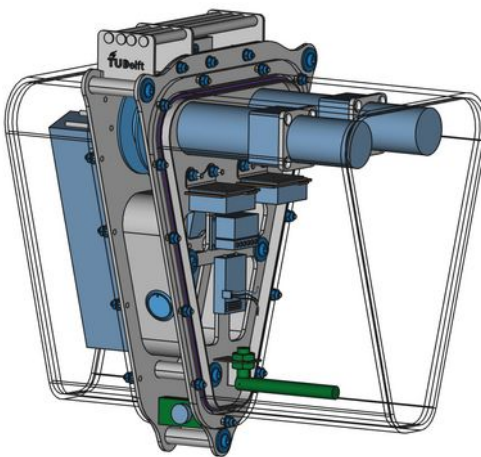
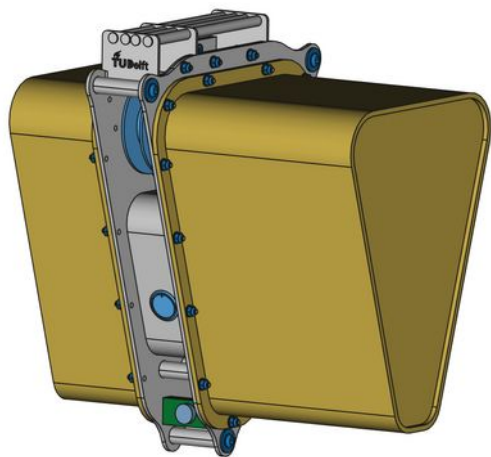
TU Delft V3 25 m²

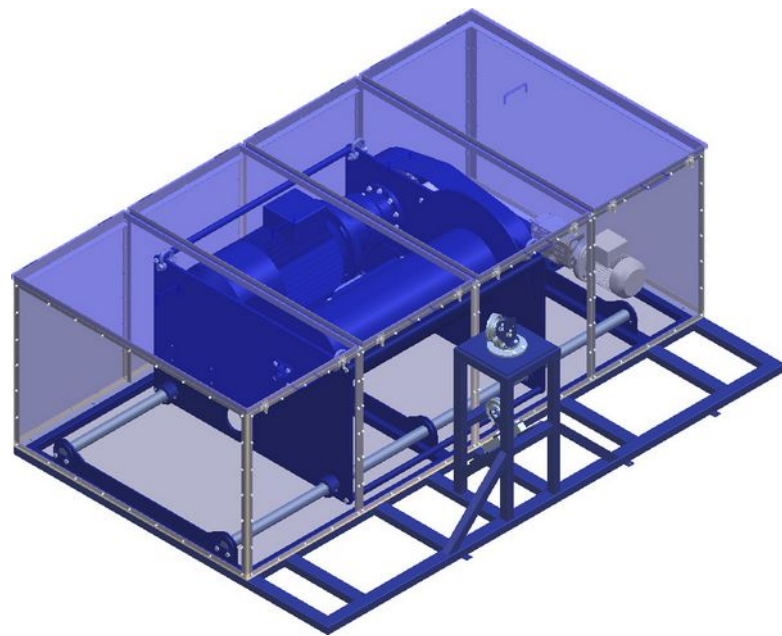
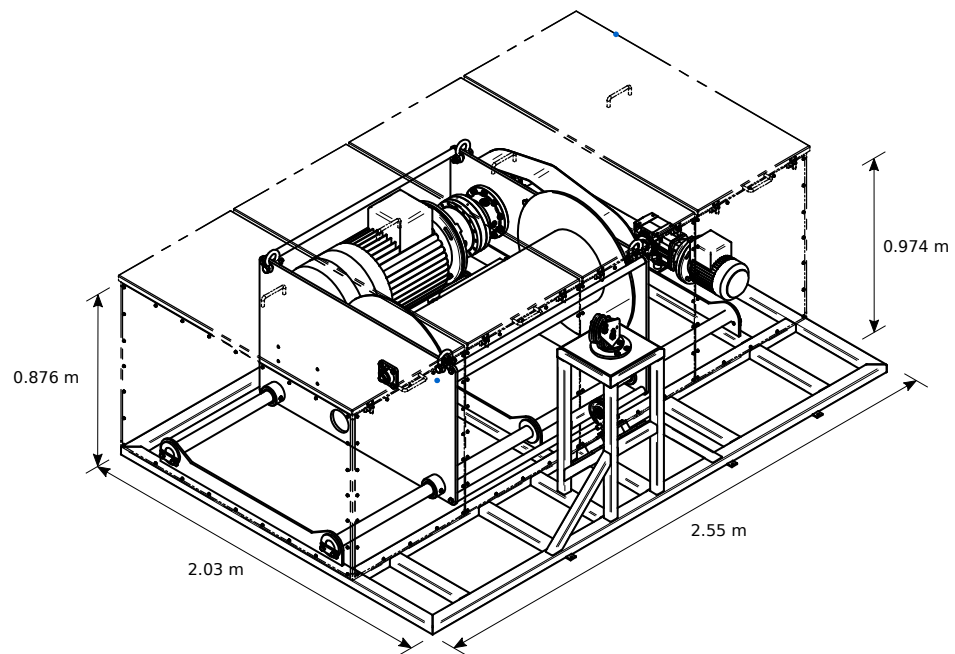


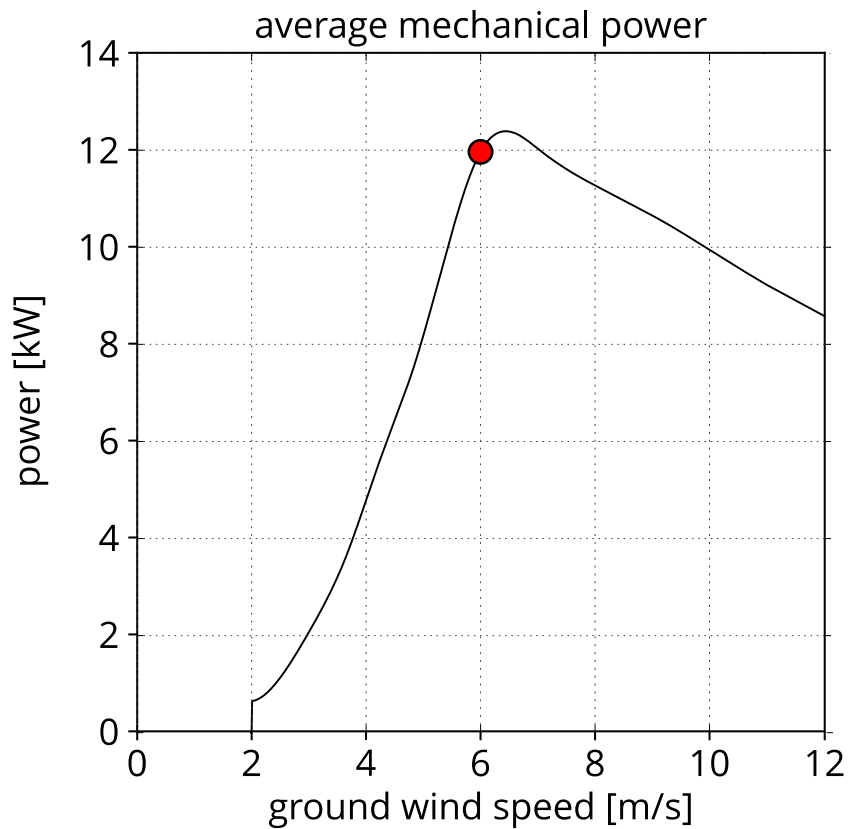
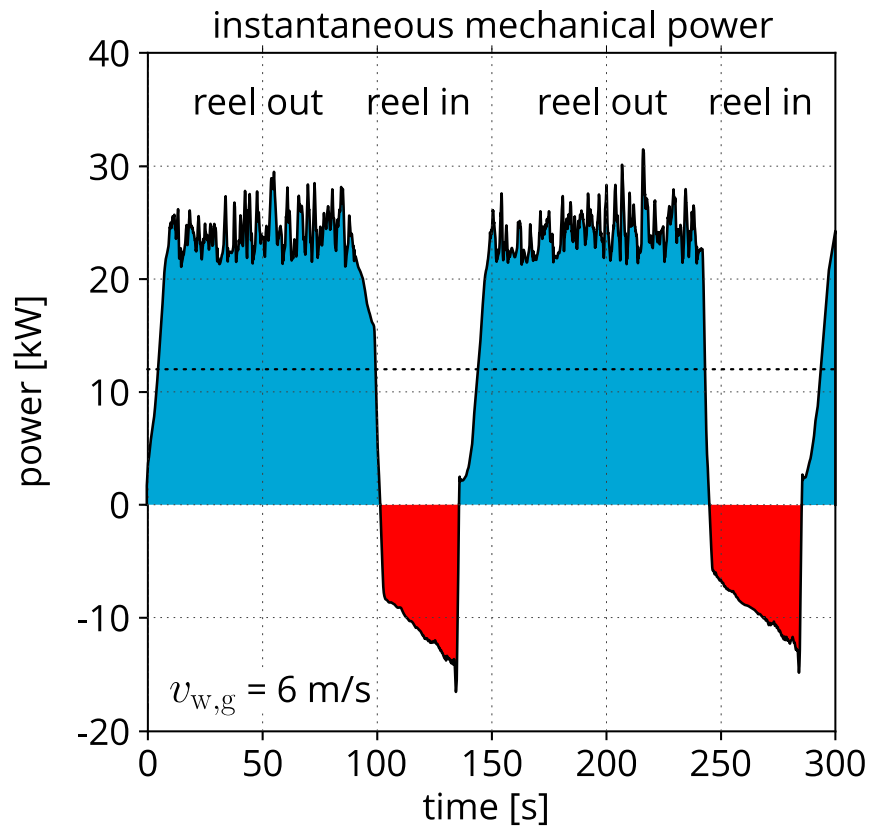
Genetrix Hydra 14 m²



TU Delft V3 25 m²







Automatic pumping cycles at Maasvlakte II of Rotterdam Harbor







Launch from upside-down position

- The following three videos show the same launch attempt on 2 August 2012
- The videos are taken from three different positions
 - GoPro video camera on the ground next to mast
 - GoPro video camera taped to the leading edge
 - Photo camera on the ground
- Weak link ruptures as result of sudden tether disengagement from mast head







40 m² kite

airborne wind energy
KITEPOWER
2017



100 kW ground station















Kite development: 25 – 40 – 60 m²

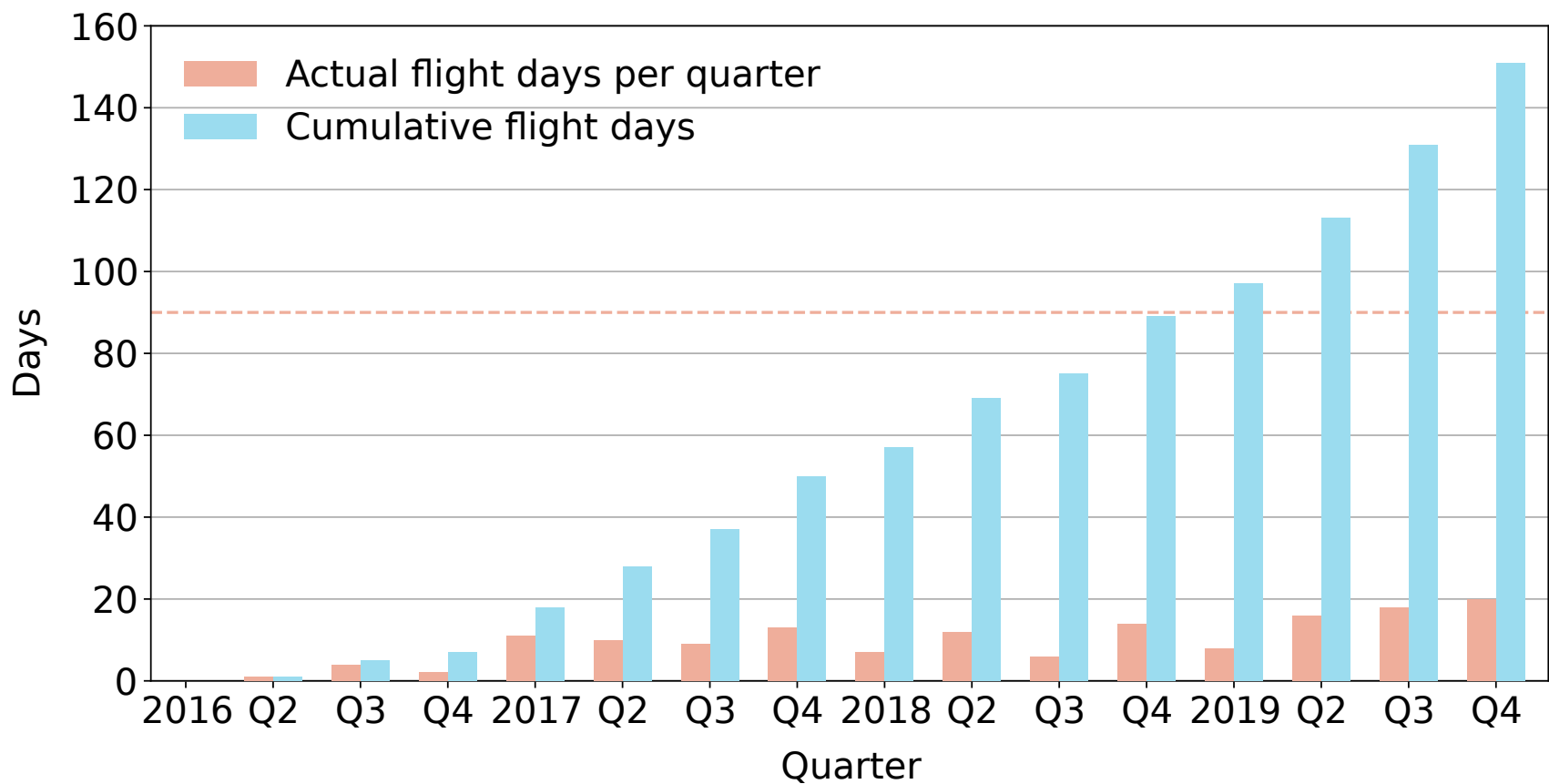


Kite development: 100 m²





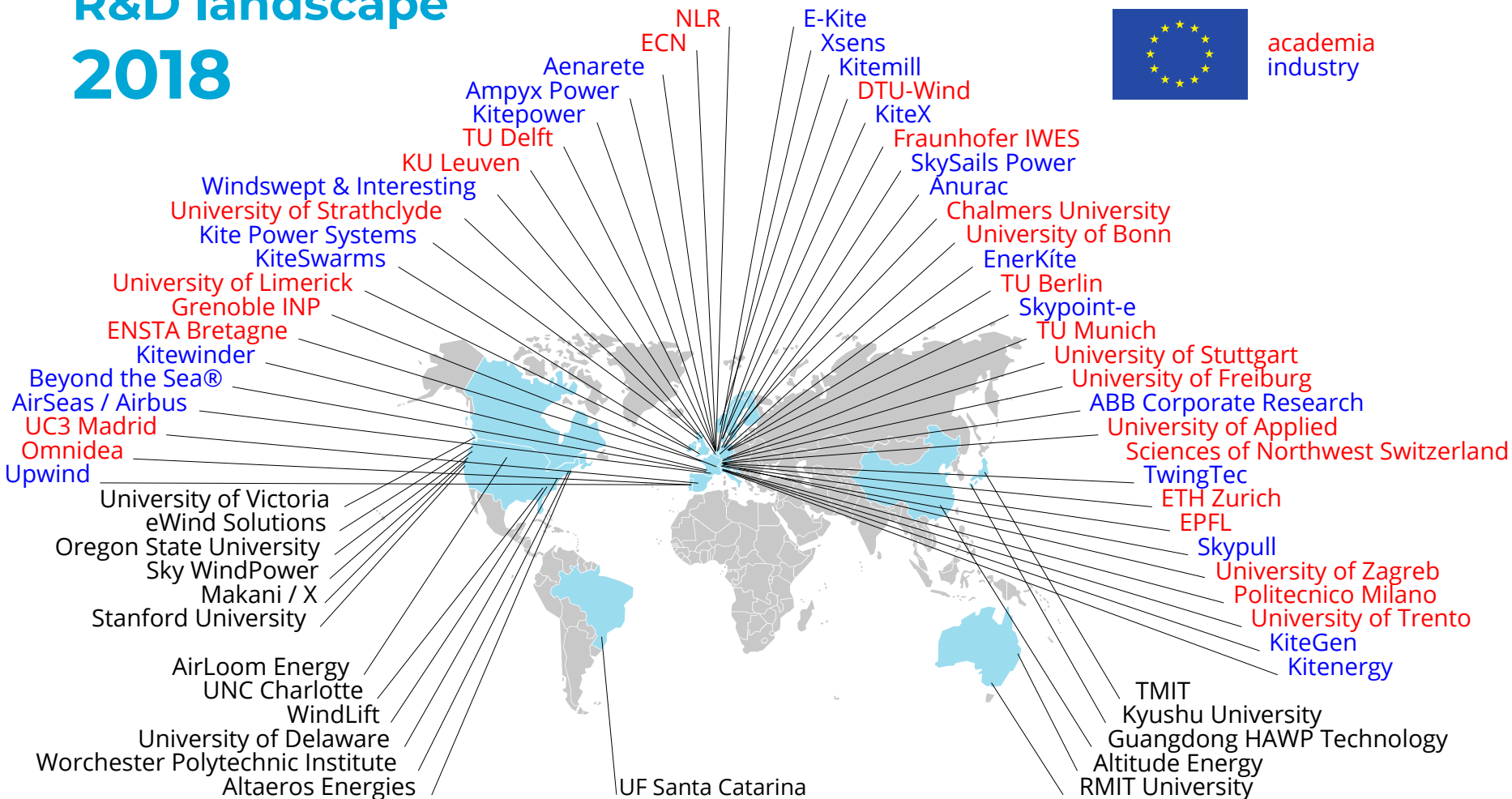
Flight days



R&D landscape 2018



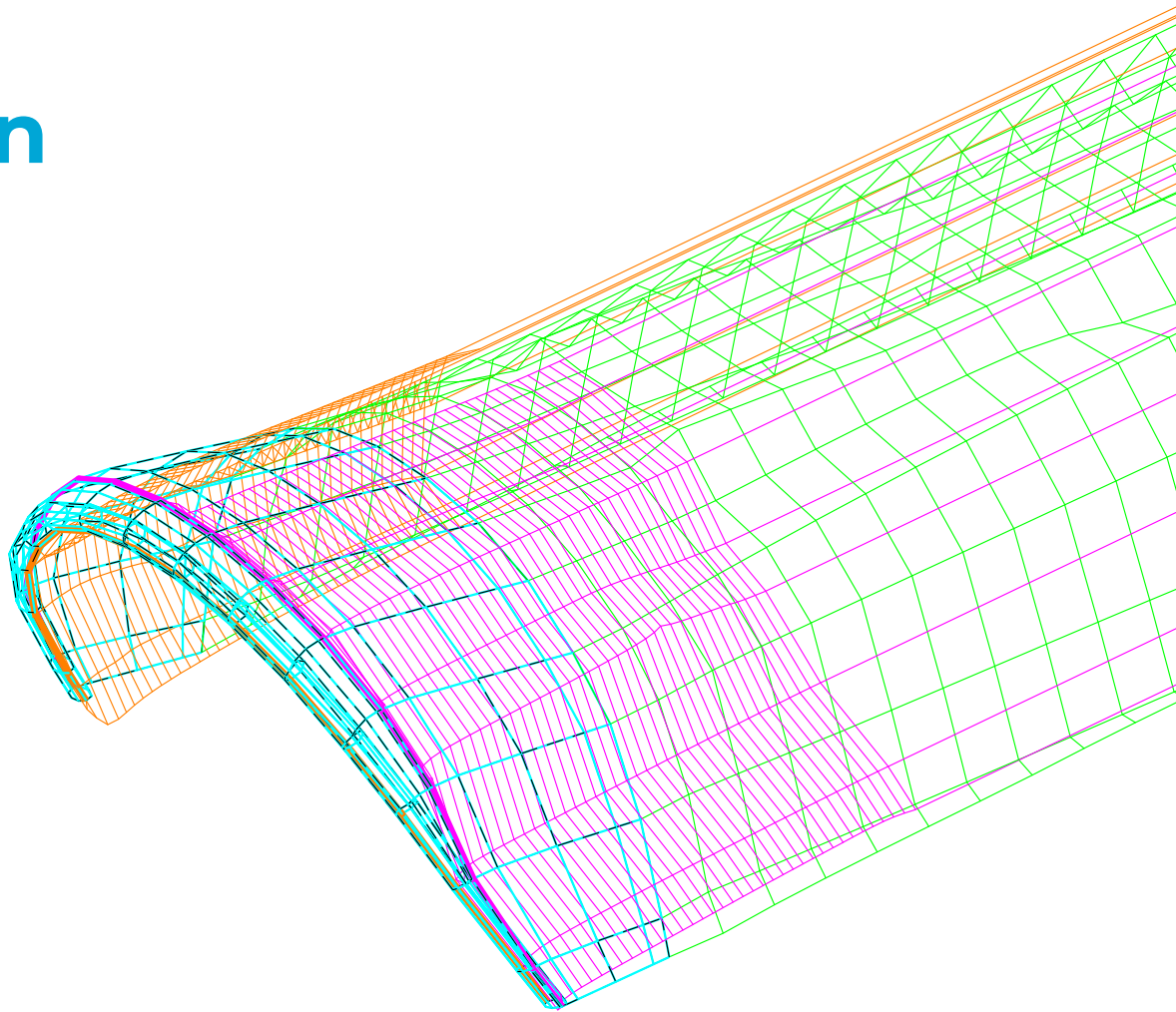
academia
industry



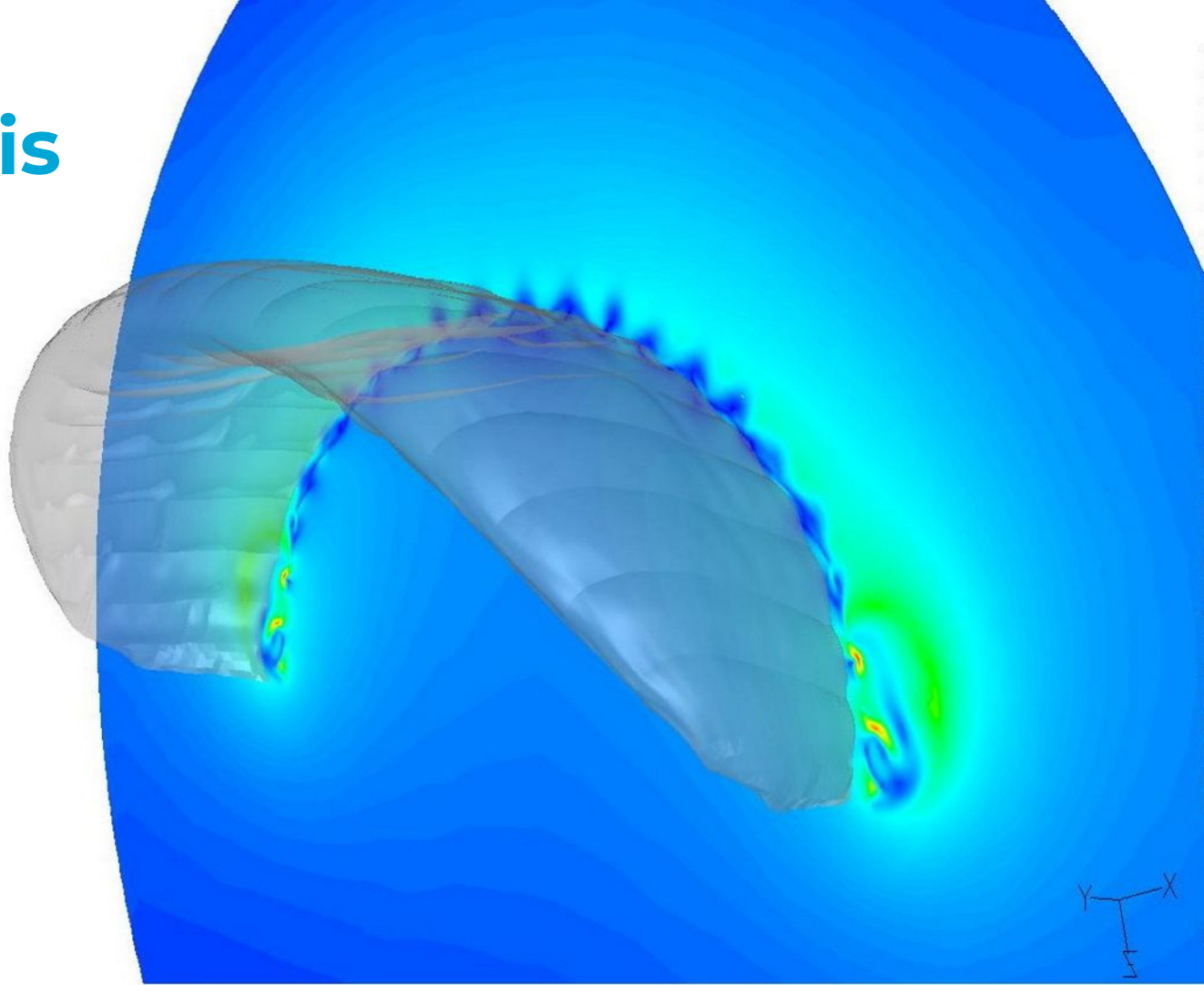
Challenges

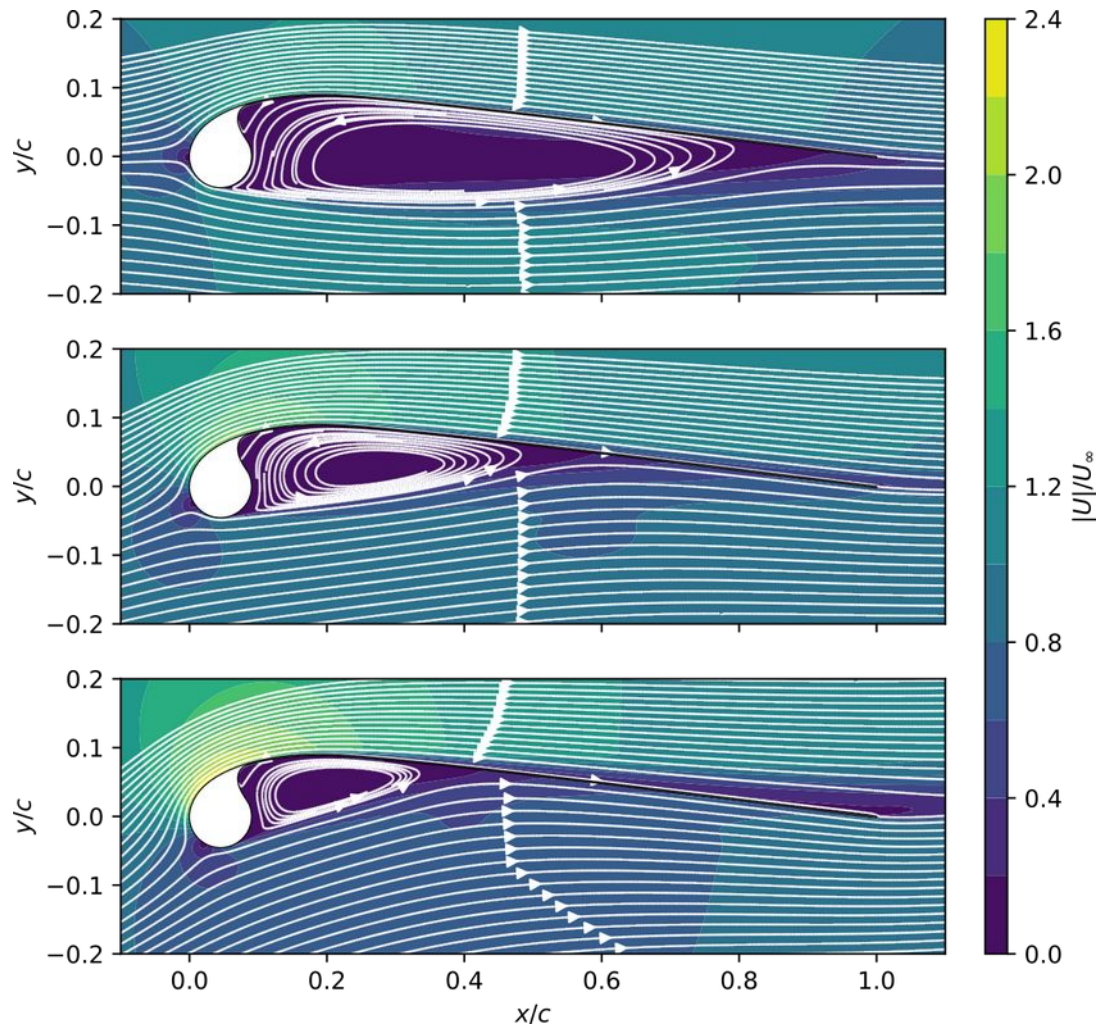
- Reliability & Safety
 - None of the projects has proven more than a few days of operation
 - Operation in kite parks
- Durability of materials
 - Tether and kite are critical components
- Regulations
 - Interference with air traffic and ground use

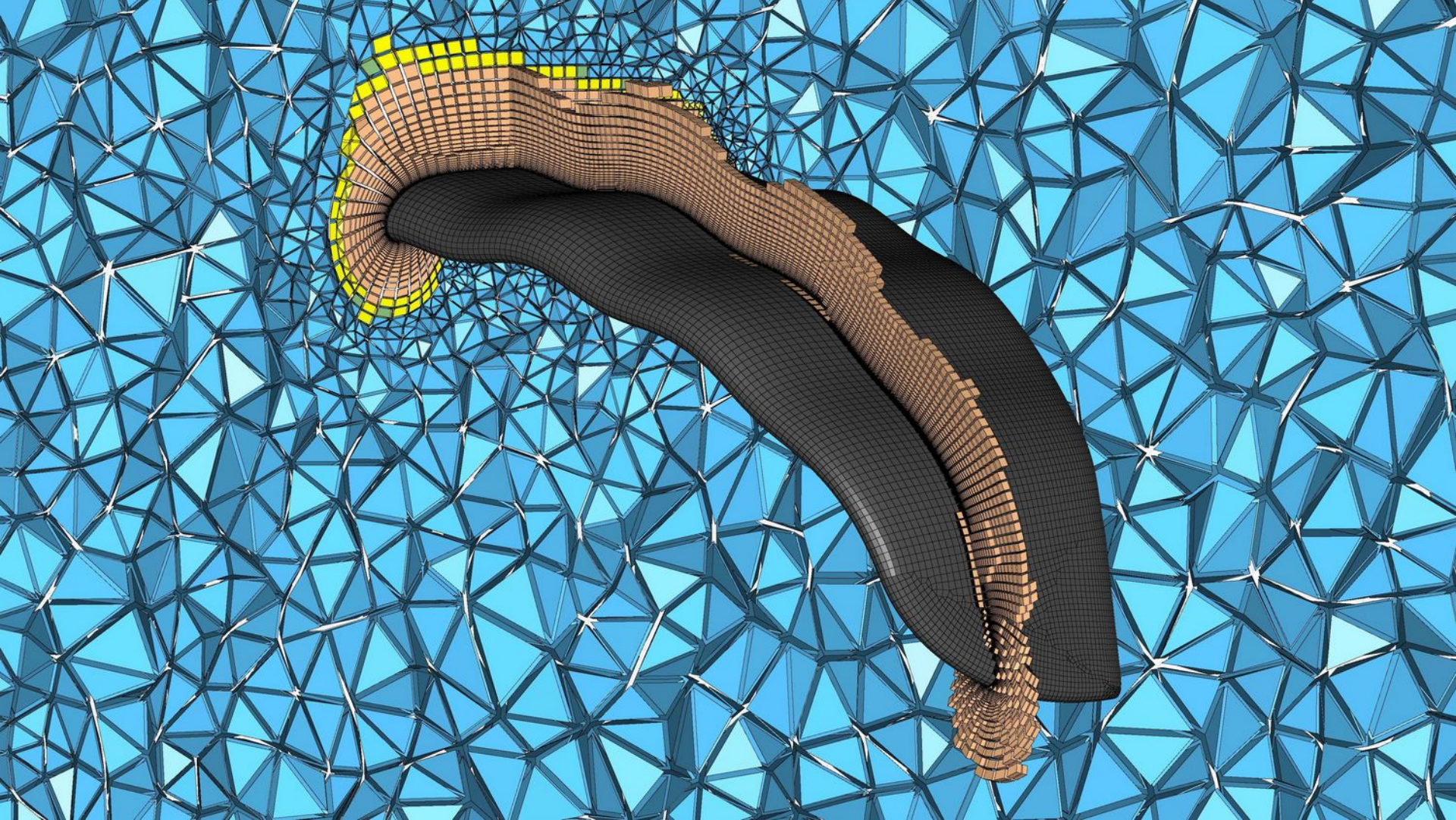
VLM simulation

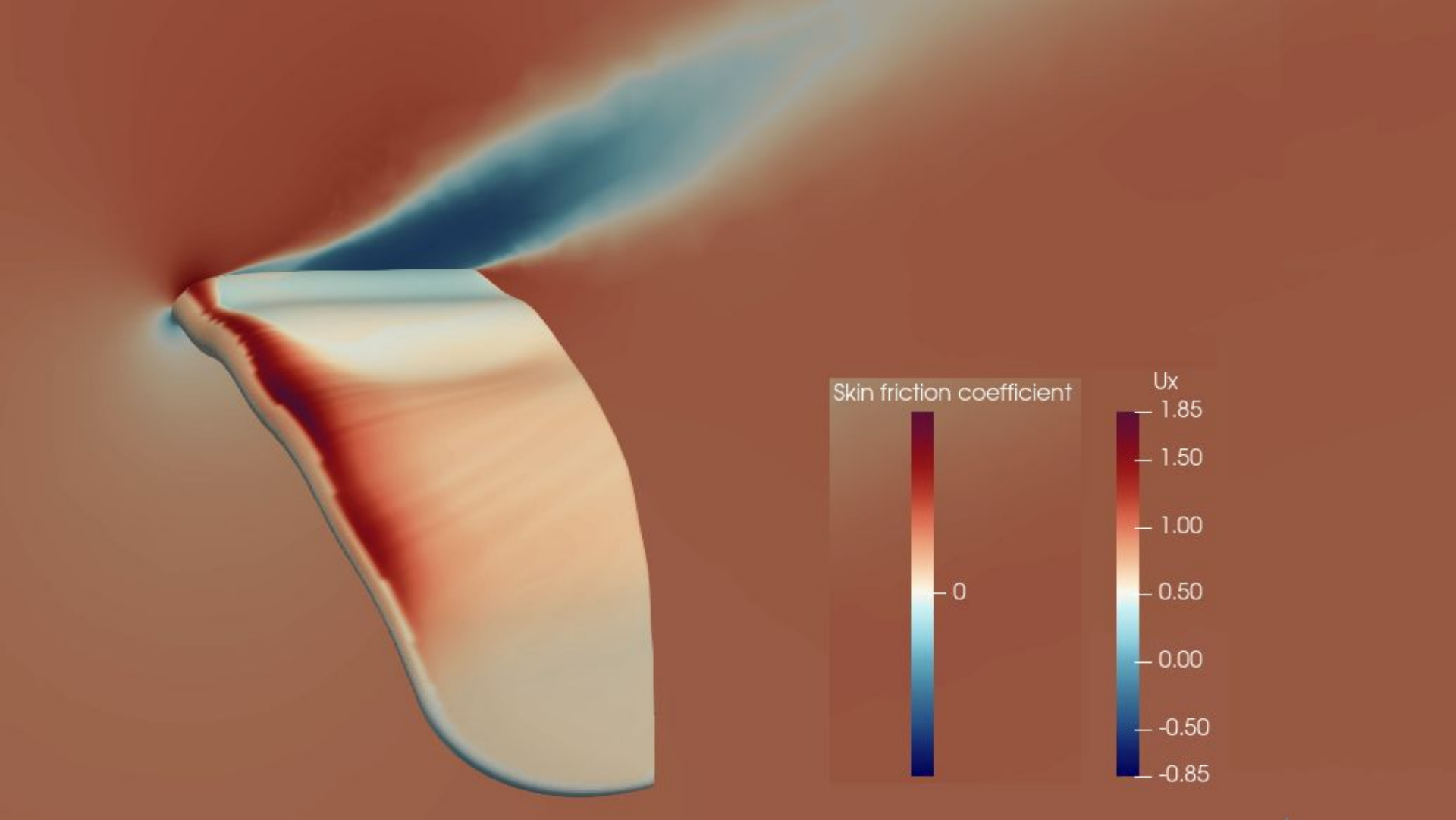


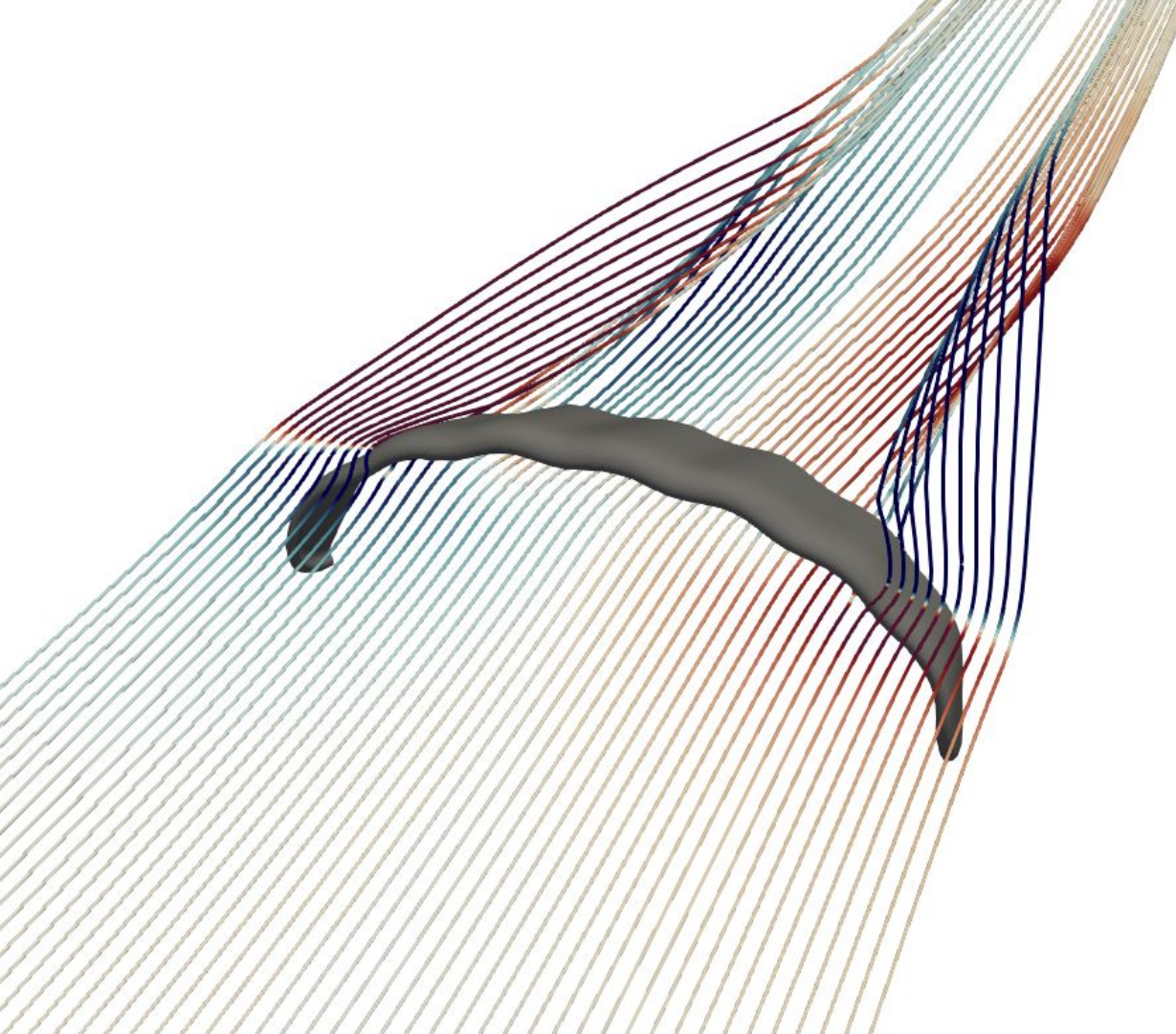
CFD analysis



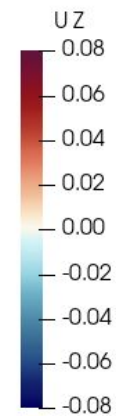


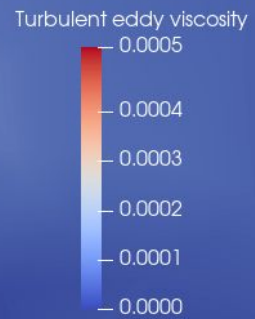


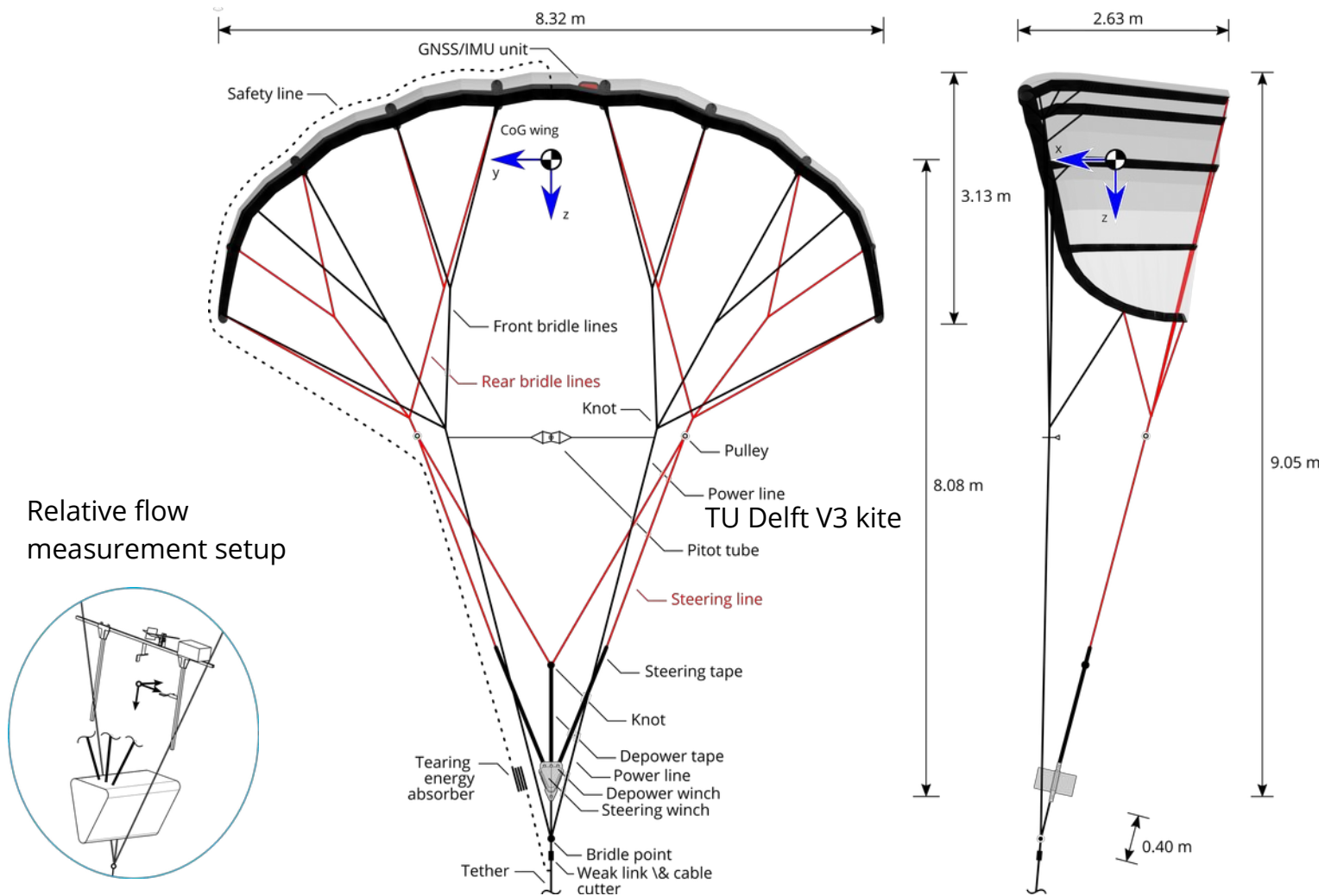




CFD simulation with OpenFOAM
Streamlines around the kite colored
With the spanwise velocity component,
computed for $Re=3 \times 10^6$ and 12° AoA



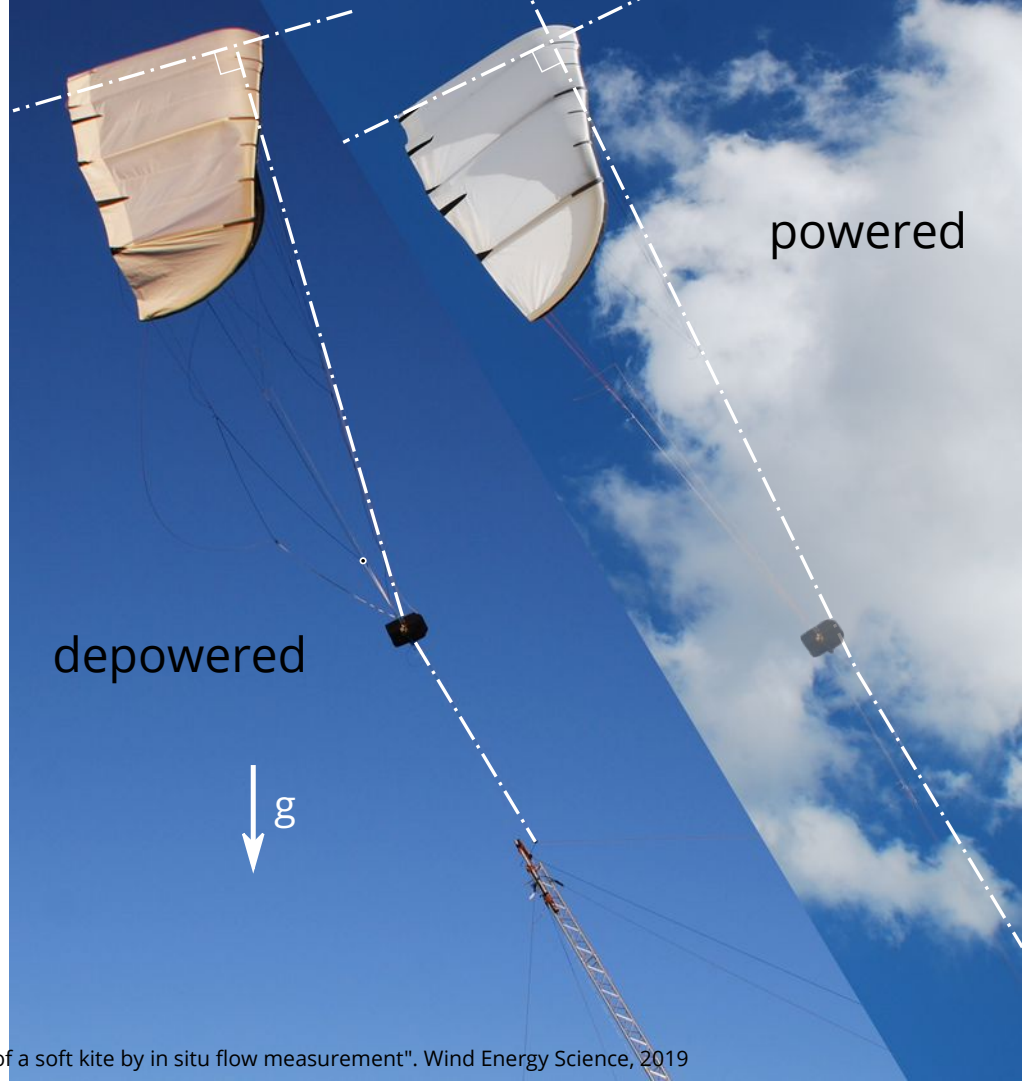






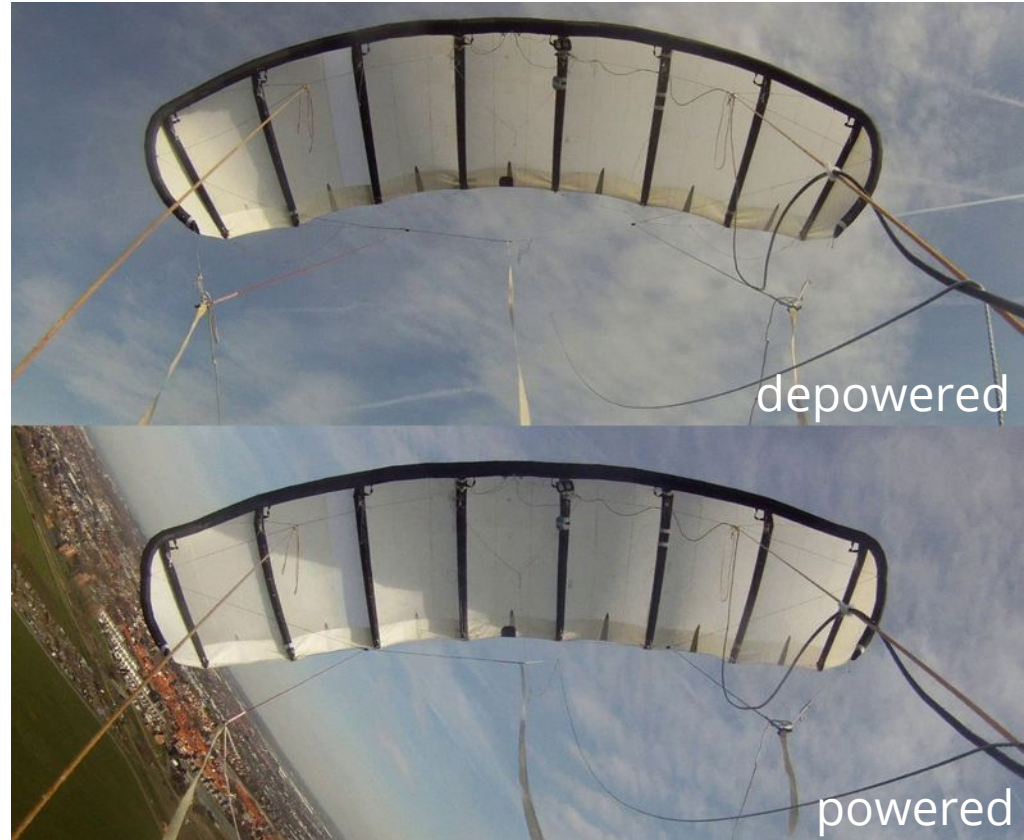
Effect of power

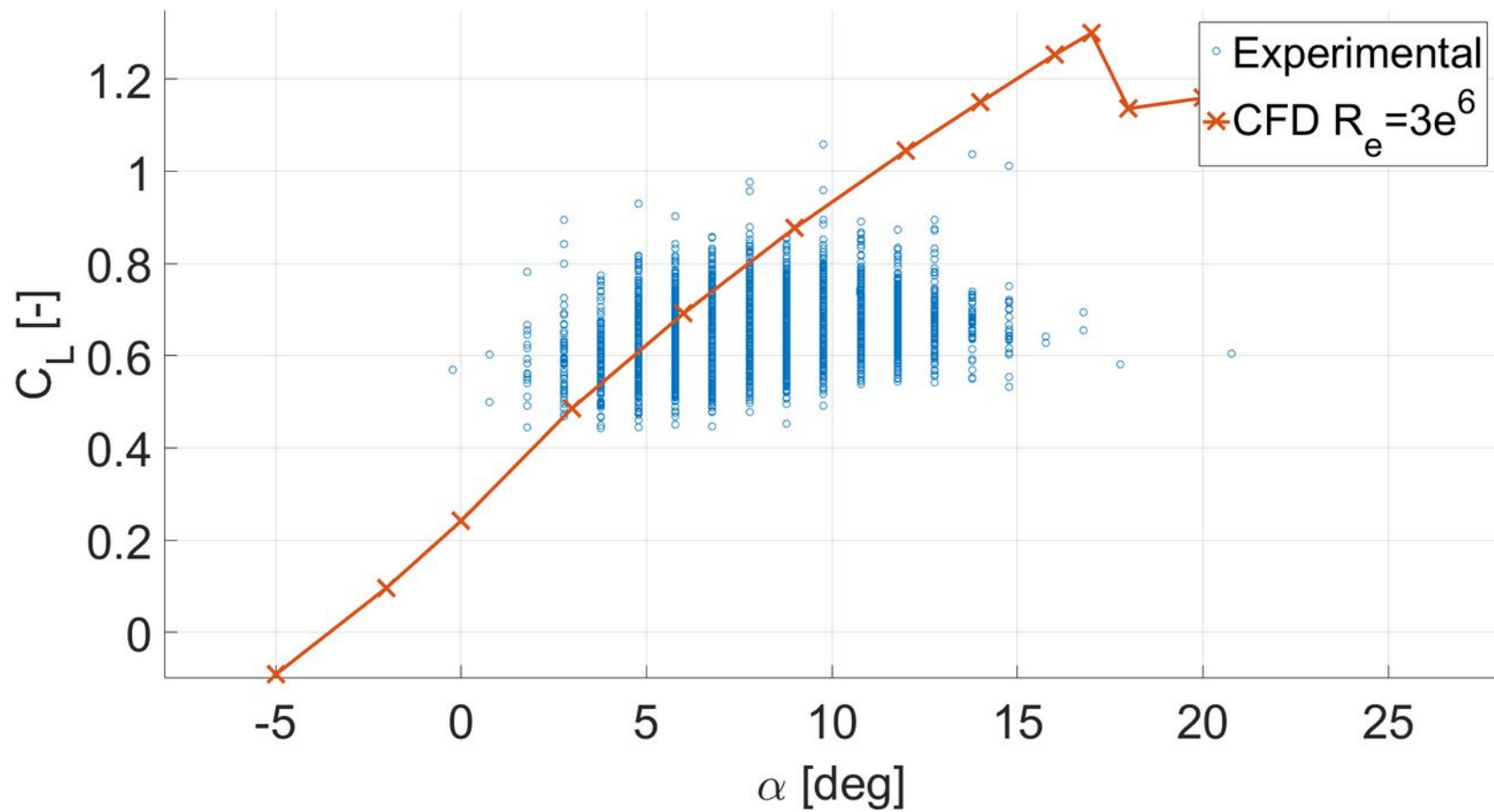
- Changes chordwise force distribution
- Powering up the wing makes wing pitch backwards

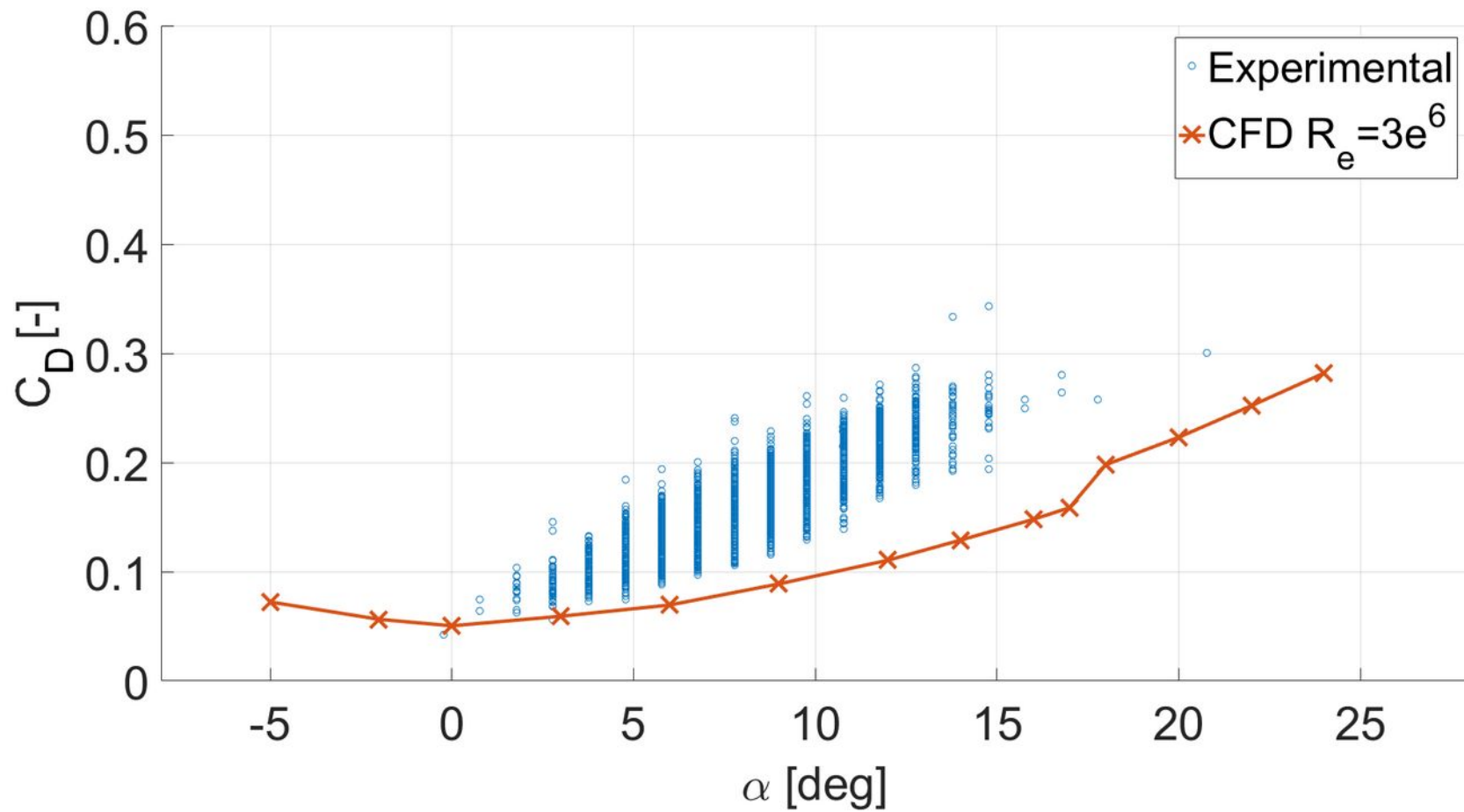


Effect of power

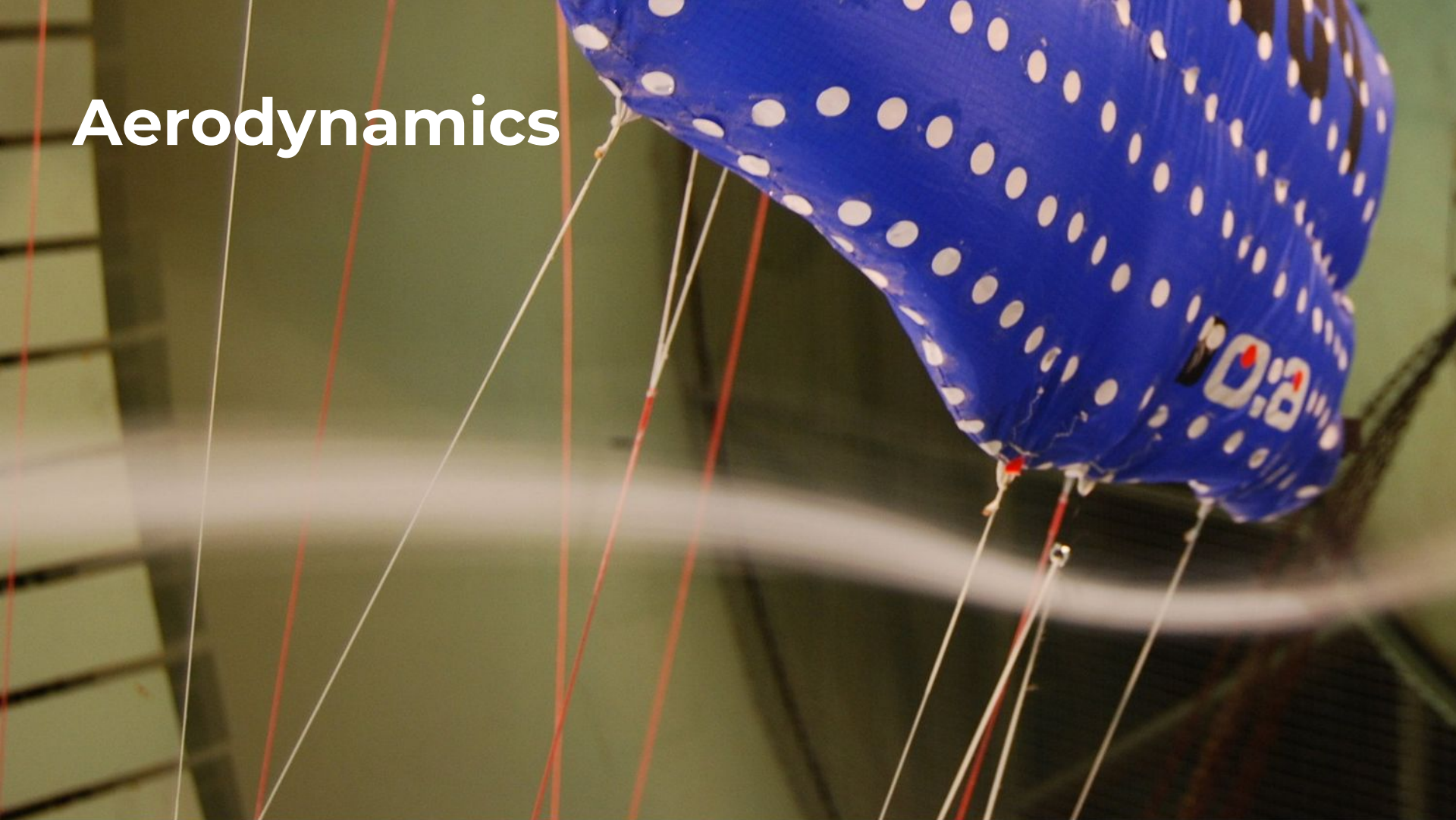
- Wing flattens
- Force increase also by area increase

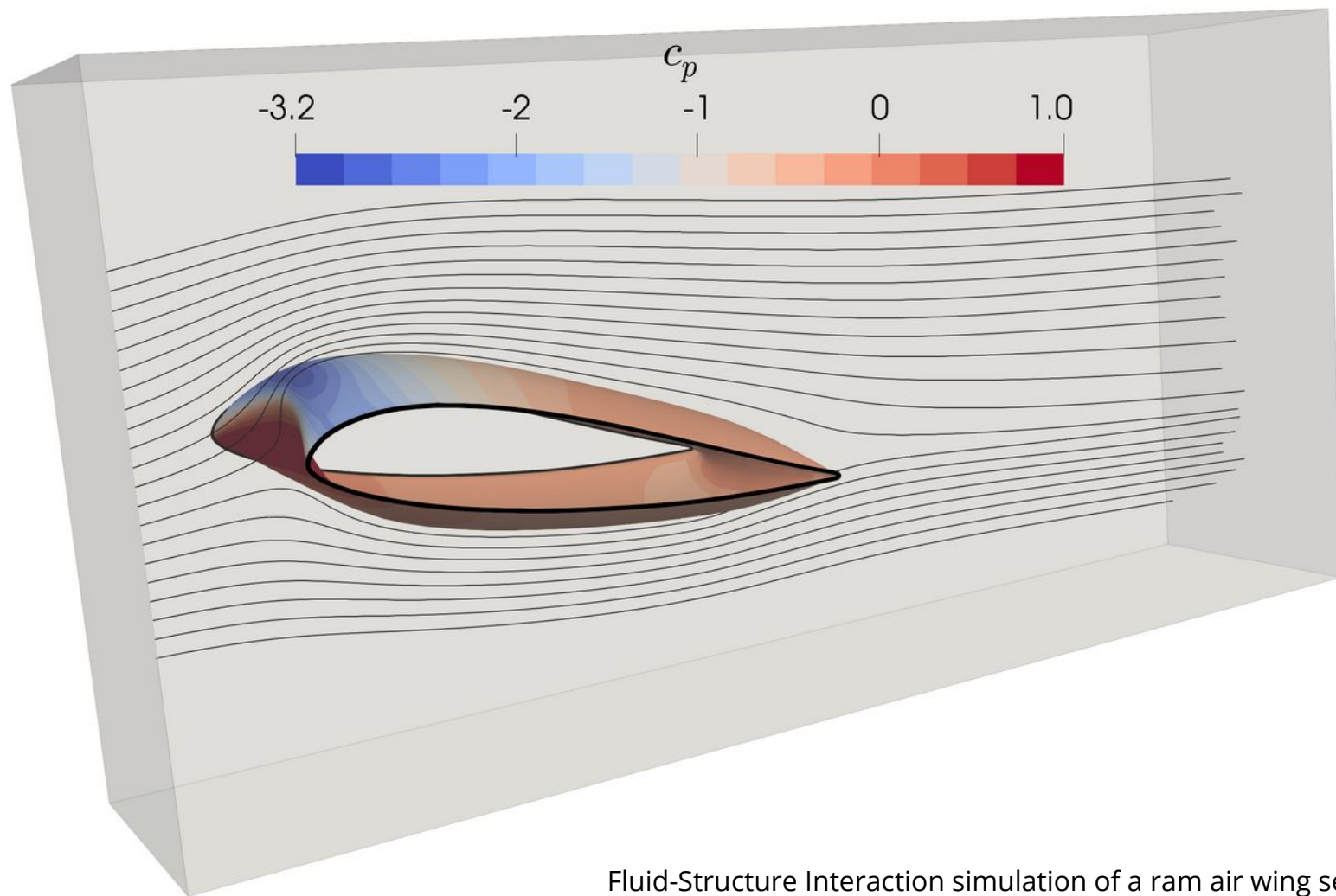






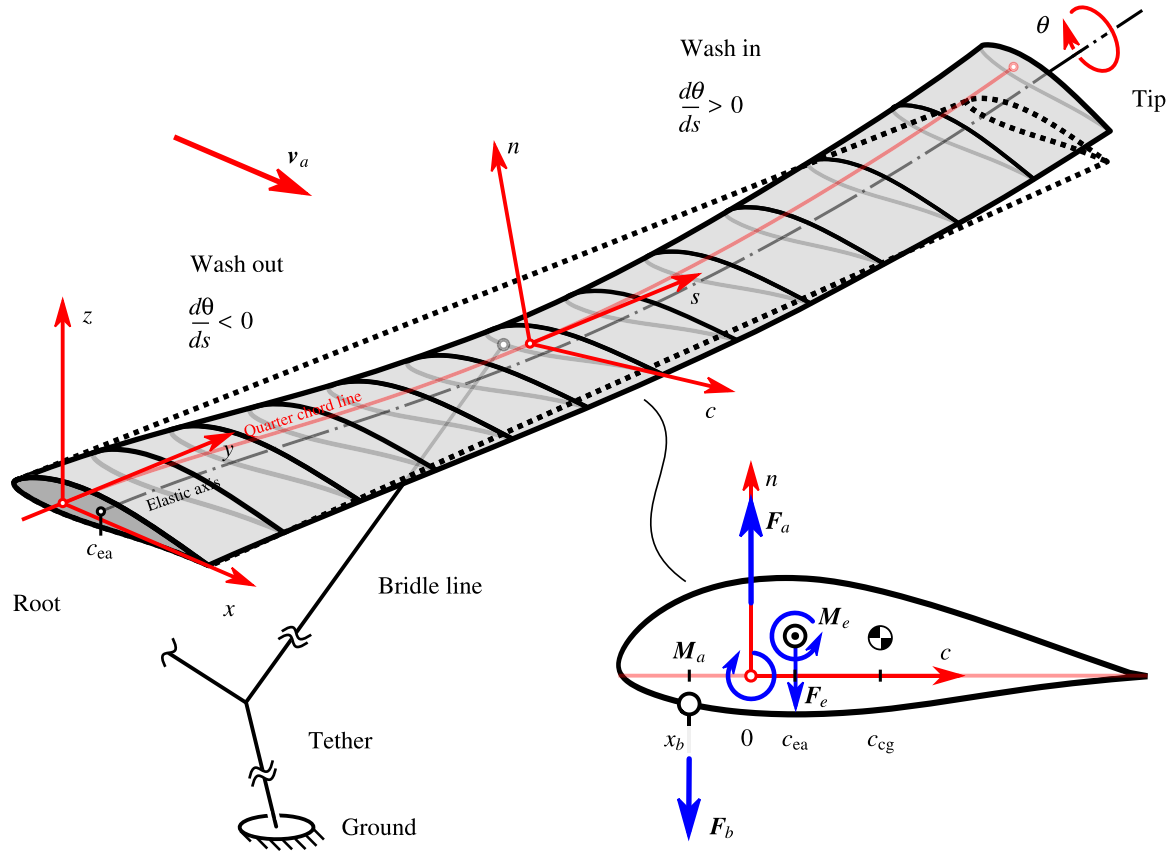
Aerodynamics





Fluid-Structure Interaction simulation of a ram air wing section

Aeroelastic bending and torsion of a half wing supported by a bridle line



The diagram illustrates a beam model for a wing-fuselage structure. Key components and forces shown include:

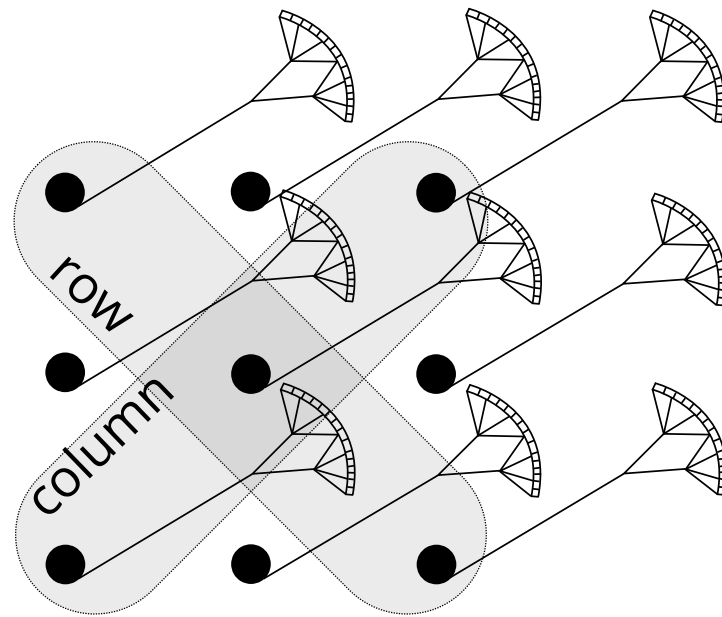
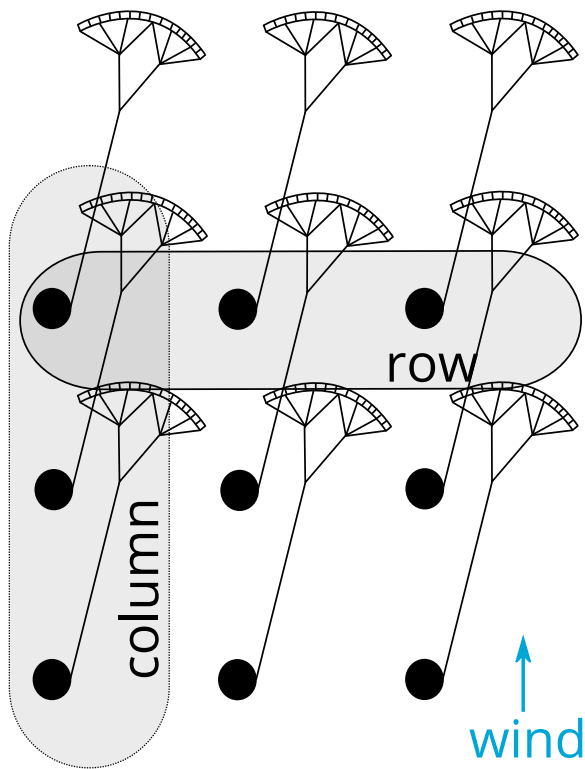
- Point mass**: A mass element on the beam.
- Angular momentum**: Represented by a circular arrow around the point mass.
- Drag force**: A force vector acting on the point mass.
- Surface beam**: The beam representing the surface of the wing.
- Unloaded wing**: The wing structure without the surface beam.
- Fuselage beam**: The beam representing the fuselage.
- Beam joint**: A connection point between the wing and fuselage beams.
- Surface beam**: The beam representing the surface of the fuselage.

Forces and moments are labeled with symbols:

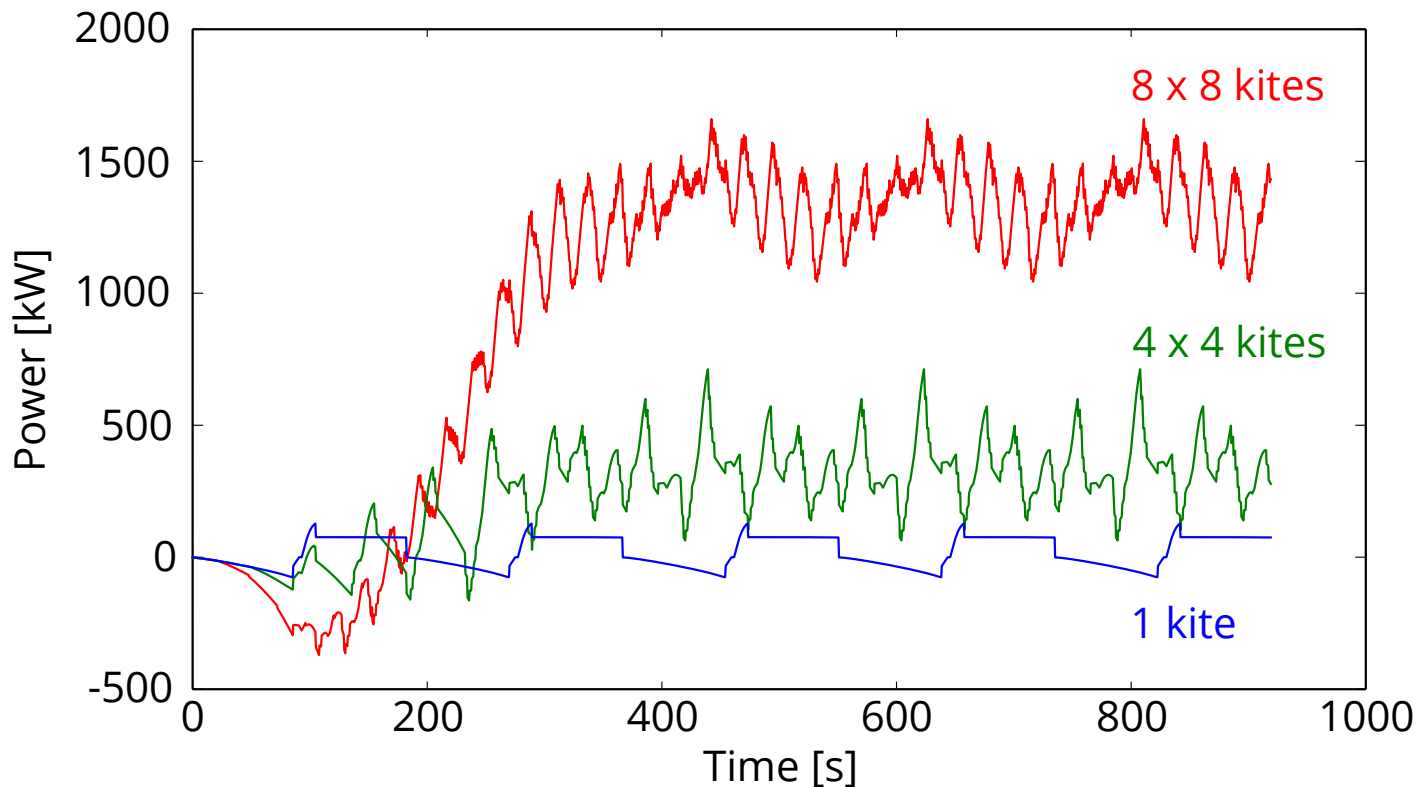
- P_{b1} , P_{i1} , P_{i2} , P_{b2} , P_k , P_{tb} , P_{tc} , P_{tg} , and P_{il} .

A coordinate system (X, Y, Z) is shown at the bottom left. A velocity vector v_a and gravity vector g are also indicated.

Kite park layout

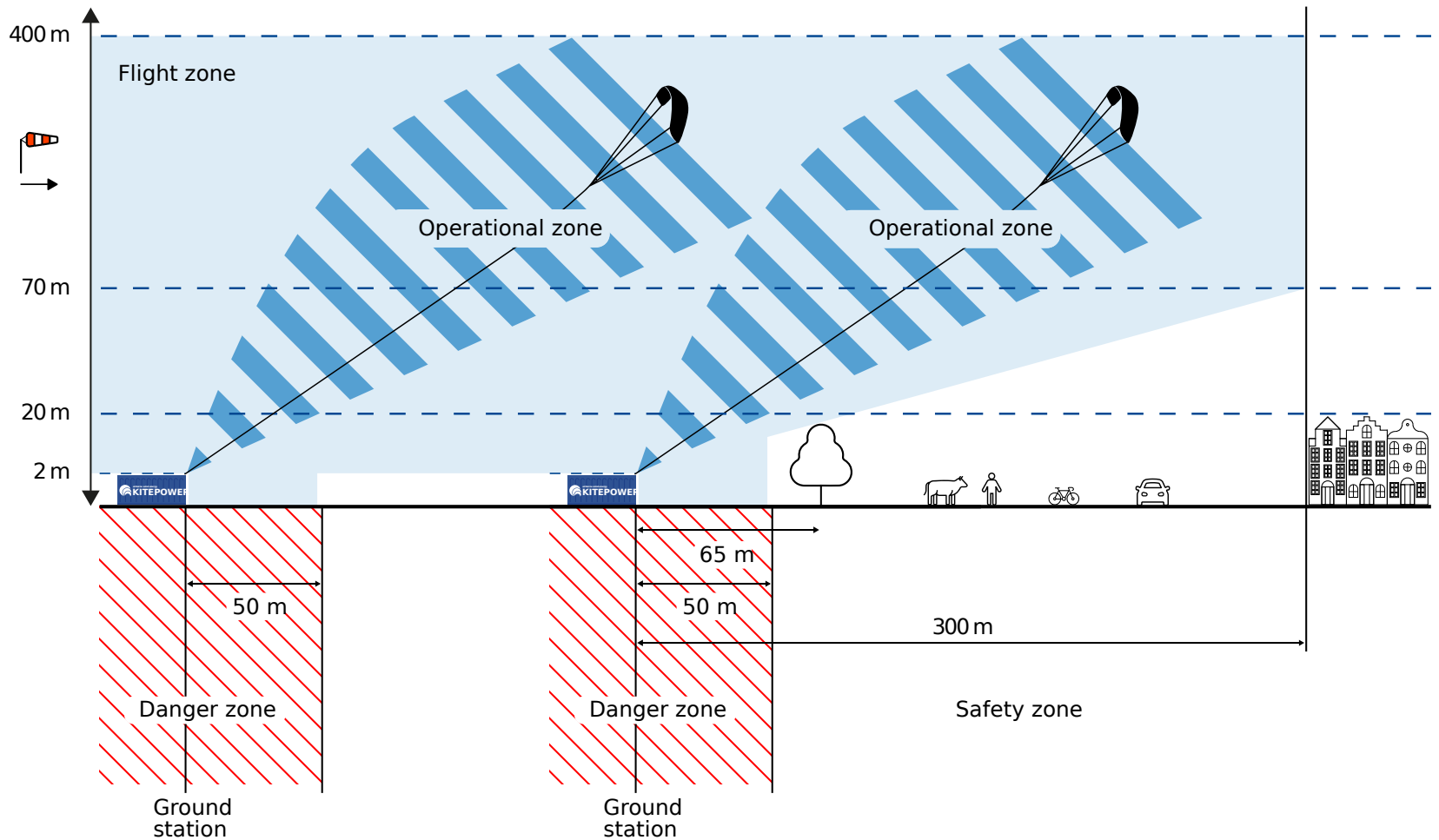


Kite park power output



Safety & reliability





(C)



(A)



(B)



(D)



(E)





ETH zürich

AirLab




Airborne Wind Energy
Reference System by DLR

DTU

TU Delft

Questions?



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-  twitter.com/kite_power
-  awesco.eu

